

Moment method, cost of fast controls for parabolic equations and Gevrey functions with compact support

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- 1 Introduction
 - Cost of controllability
 - Diagonal operators
 - The moment method

- 2 The cost of fast controls for fractional heat equations
 - Presentation
 - A lower bound
 - The Bray-Mendelbrojt Construction of functions with compact support

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Linear control system

Let $(H, \langle \cdot, \cdot \rangle_H)$ be some Hilbert space and $(A, \mathcal{D}(A))$ some closed unbounded operator with dense domain on H .

We assume that A et A^* are dissipative ($\Re(\langle Ax, x \rangle_H) \leq 0$), so that A is the generator of a strongly continuous semigroup.

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Let $(U, \langle \cdot, \cdot \rangle_U)$ another Hilbert space . Let $B \in \mathcal{L}_c(U, \mathcal{D}(A^*))'$.

Let $T > 0$ some time, $y^0 \in H$ and $u \in L^2((0, T), U)$.

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Linear control system:

$$\{ \dot{y} = Ay + Bu. \quad (\text{Syst-Cont})$$

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Linear control system:

$$\{ \dot{y} = Ay + Bu. \quad (\text{Syst-Cont})$$

We assume that there exists $C(t)$ such that for every $z \in \mathcal{D}(A^*)$, (admissibility condition)

$$\int_0^t \|B^* e^{tA^*} z\|_U^2 \leq C(t) \|z\|_H^2, \quad \forall z \in \mathcal{D}(A^*), \forall t \in [0, T]. \quad (\text{Adm})$$

In this case, $B^* e^{tA^*}$ can be extended in $\mathcal{L}_c(H, U)$.

Admissibility and well-posedness

Définition

A **solution** of (Syst-Cont) with initial $y^0 \in H$ is a function $y \in C^0([0, T], H)$ verifying $y(0) = y^0$ and such that for every τ in $[0, T]$ and z^τ in H , we have

$$\langle y(\tau), z^\tau \rangle_H - \langle y^0, e^{\tau A^*} z^\tau \rangle_H = \int_0^\tau \langle u(t), B^* e^{(\tau-t)A^*} z^\tau \rangle_U dt. \quad (\text{Def-Sol})$$

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Théorème (Weiss'89)

We assume B **admissible** (i.e. (Adm) holds). For every $y^0 \in H$ and $u \in L^2((0, T), U)$, (Syst-Cont) with initial condition y^0 admits a **unique solution** $y \in C^0([0, T], H)$ verifying

$$\|y\|_{C^0([0, T], H)} \leq C(T)(\|y^0\|_H + \|u\|_{L^2((0, T), U)}).$$

Null controllability

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(Syst-Cont) is null controllable at time T if for every $y^0 \in H$, there exists (y, u) solution of (Syst-Cont) such that $y(0) = y^0$ and $y(T) = 0$.

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Assume that (Syst-Cont) is controllable. In general, the control u driving y^0 to 0 at time T is **not unique**. Let us consider the set of controls

$$\mathcal{E}_{adm}(y^0) := \{\tilde{u} \text{ s.t. } (\tilde{y}, \tilde{u}) \text{ ver. (Syst-Cont), } \tilde{y}(0) = y^0 \text{ and } \tilde{y}(T) = 0\}.$$

Let us consider the following optimization Problem:

$$\min_{\tilde{u} \in \mathcal{E}_{adm}(y^0)} J(\tilde{u}) := \min_{\tilde{u} \in \mathcal{E}_{adm}(y^0)} \frac{1}{2} \int_0^T \|\tilde{u}(t)\|_U^2 dt. \quad (\text{Cont-Opt})$$

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Proposition

There exists a unique solution $u_{opt}(y^0)$ to the Problem (Cont-Opt).

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There exists a unique solution $u_{opt}(y^0)$ to the Problem (Cont-Opt).

Proof: $\mathcal{E}_{adm}(y^0)$ is an **affine subspace** of U and is also **closed**. u_{opt} is then the orthogonal projection of 0 on $\mathcal{E}_{adm}(y^0)$.

Definition of the cost of the control

We consider $\Gamma : y^0 \mapsto u_{opt}(y^0)$. This application is linear continuous and we call C_T its operator norm, that we call the **cost of the control** at time T .

$$C_T := \sup_{\|y^0\|=1} \min_{\tilde{u} \in \mathcal{E}_{adm}(y^0)} \int_0^T \|\tilde{u}(t)\|_U^2 dt.$$

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C_T quantifies the **minimal energy** needed to bring any initial condition to 0. It is the smallest constant C such that for every $y^0 \in H$, there exists (\tilde{y}, \tilde{u}) verifying (Syst-Cont) such that $\tilde{y}(0) = y^0$ and $\tilde{y}(T) = 0$ with

$$\|u\|_U \leq C \|y^0\|_H.$$

Link with the inverse problems

If we call O_T the largest constant C such that

$$\int_0^T \|B^*\varphi(t)\|^2 dt \geq C \|\varphi^T\|,$$

one can prove that we have the relation

$$O_T = \frac{1}{C_T}.$$

Hence, C_T also quantifies the **accuracy of the reconstruction** of the final data φ^T thanks to the observation $\int_0^T \|B^*\varphi(t)\|^2 dt$.

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Goal

Estimate precisely the behavior of **fast controls**, i.e. the asymptotic of C_T as $T \rightarrow 0$.

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Diagonal operators and scalar controls

From now on we assume A **negative selfadjoint**.

Normalized eigenvectors and eigenvalues: $(e_j, -\lambda_j)$, where $\lambda_j > 0$. From now on,

$$U = \mathbb{R}, \quad Bu = bu,$$

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Going back to (Def-Sol), defining the solutions of (Syst-Cont) is equivalent to have for every k and every $t \in (0, T)$

$$\langle y(t, x), e_k \rangle_H = a_k e^{-\lambda_k t} + b_k \int_0^t e^{-\lambda_k(t-s)} u(s) ds. \quad (\text{Def-Sol-Diag})$$

A criterium to obtain admissibility

Définition

We say $(\lambda_n)_{n \in \mathbb{N}^*}$ is *regular* if

$$\gamma((\lambda_n)_{n \in \mathbb{N}^*}) := \inf_{m \neq n} |\lambda_m - \lambda_n| > 0. \quad (\text{Regul})$$

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Théorème (Ho-Russell'83)

Assume that $(\lambda_n)_{n \in \mathbb{N}^*}$ is regular. If $\|(b_k)_{k \in \mathbb{N}^*}\|_\infty < +\infty$, then b is admissible.

Ex: fractional heat equation with “boundary” control (1)

Consider Δ with domain $D(\Delta) := H_0^1(0, L)$ and **state space** $H := H^{-1}(0, L)$. $-\Delta : D(\Delta) \rightarrow H^{-1}(0, L)$ is a positive definite operator with compact resolvent, the k -th eigenvalue is $\frac{k^2\pi^2}{L^2}$, with eigenvector $e_k(x) := \frac{\sqrt{2}k\pi}{L^{3/2}} \sin\left(\frac{k\pi x}{L}\right)$. Thanks to the continuous functional calculus for positive self-adjoint operators, one can define any **positive power** of $-\Delta$. Let us consider here some $\alpha > 1$.

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We consider

$$\begin{cases} y_t = -(-\Delta)^{\alpha/2}y + bu & \text{in } (0, T) \times (0, L), \\ y(0, \cdot) = y^0 & \text{in } (0, L), \end{cases} \quad (\text{Heat-Frac})$$

where b is a scalar control operator to be defined. We call

$$\lambda_k := \frac{k^\alpha \pi^\alpha}{L^\alpha}.$$

$\{\lambda_k\}_{k \in \mathbb{N}^*}$ is **regular**.

Ex: fractional heat equation with “boundary” control (2)

We set

$$b := (\varphi \in \mathcal{D}(A) \mapsto (\Delta^{-1}\varphi)_x(0)), \text{ i.e.}$$

$$b := -(\partial_x \delta_0) \circ \Delta^{-1},$$

if $\alpha = 2n$ with $n \in \mathbb{N}$, b corresponds to impose $\Delta^n y|_{x=0} = u(t)$.

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$$\begin{aligned} b_k &= (\Delta^{-1} e_k)_x(0) \\ &= \frac{L^2}{k^2 \pi^2} \frac{\sqrt{2} k \pi}{L^{3/2}} \sin\left(\frac{k \pi x}{L}\right)_x(0) \\ &= \frac{L^2}{k^2 \pi^2} \frac{\sqrt{2} k \pi}{L^{3/2}} \frac{k \pi}{L} \\ &= \frac{\sqrt{2}}{\sqrt{L}} \end{aligned}$$

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In this case we have

$$\|b_k\|_\infty < \infty,$$

and the operator is **admissible**.

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The moment method (Fattorini-Russell'71)

Taking into account (Def-Sol-Diag), imposing $y(T, x) = 0$ is now equivalent to impose for every k that

$$a_k e^{-\lambda_k T} + b_k \int_0^T e^{-\lambda_k(T-t)} u(t) dt = 0.$$

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A necessary condition is that all the $b_k \neq 0$ that for every k we have

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Consider a **biorthogonal** family to the family of exponentials $\{t \mapsto e^{\lambda_n t}\}$ in $L^2(0, T)$, i.e. a family $\{\psi_m\}_{m \in \mathbb{N}^*} \in L^2(0, T)$ such that

$$\langle e^{\lambda_k t}, \psi_l \rangle_{L^2(0, T)} = \delta_{kl}. \quad (\text{Biorth})$$

Creating bi-orthogonal functions

It is then enough to set

$$u(t) := - \sum_{k \in \mathbb{N}^*} (a_k/b_k) \psi_k(t),$$

as soon as this expression is meaningful (for example if $|b_k| \geq C > 0$).
(Biorth) is equivalent to prove

$$\mathcal{F}(\psi_j)(-i\lambda_k) = \delta_{jk},$$

(where \mathcal{F} is the **Fourier transform**) as soon as the support of ψ_j is included in $(0, T)$ and ψ_j is in L^2 .

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Simplest idea: create a function which has $-i\lambda_k$ as **simple roots**:

$$\Psi(z) := \prod_{k=1}^{\infty} (1 - iz/\lambda_k).$$

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$$\Psi(z) := \prod_{k=1}^{\infty} (1 - iz/\lambda_k).$$

We then set

$$J_k(z) := \frac{\Psi(z)}{\Psi'(-i\lambda_k)(z + i\lambda_k)}$$

and we look at $\mathcal{F}^{-1}(J_k)$.

The case of the fractional heat equation

We go back to (Heat-Frac) and to simplify we choose $L = \pi$, so that $\lambda_k = k^\alpha$.

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On the real axis we can prove

$$\sum_{k=1}^{\infty} \ln \left(1 + \frac{x^2}{k^{2\alpha}} \right) \leq |x|^{2/\alpha} \int_1^{\infty} \frac{dt}{t^{1/(2\alpha)(1+t)}} \leq |x|^{2/\alpha} \frac{\pi}{\sin \left(\frac{\pi}{2\alpha} \right)}.$$

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We deduce that

$$|J_k(x)| \simeq C(k) e^{-\frac{\pi}{2 \sin \left(\frac{\pi}{2\alpha} \right)} |x|^{1/\alpha}},$$

and this estimate is **optimal** at infinity.

⇒ **cannot obtain** a L^2 function by taking the inverse Fourier transform.

A remedy: the Paley-Wiener Theorem

Theorem (Paley-Wiener'33)

*F is the Fourier transform of a L^2 function with compact support in $[-A, A]$ if and only if $F \in L^2(\mathbb{R})$ and F is of **exponential type** A , i.e. F is an entire function verifying*

$$|F(z)| \lesssim e^{A|z|}.$$

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The idea is then to multiply J_k by some entire function M_k (called **multiplier**) which ensures that $M_k J_k$ is still of **exponential type**, has the **same roots as J_k** and is sufficiently **decreasing** on the real axis, i.e. such that $M_k J_k \in L^2(\mathbb{R})$.

Link with Gevrey functions (1)

In the case of the fractional heat equation we know that

$$J_k \simeq \exp(K|x|^{1/\alpha})$$

for some $K > 0$. We want to obtain a function $M_k J_k$ which is in $L^2(\mathbb{R})$
 \Rightarrow We need $M_k \simeq \exp(-K|x|^{1/\alpha})$ at infinity. This exactly means that M_k has to be the **Fourier transform of some function** G_k which has to be **Gevrey of order α** , i.e. verifying

$$\|G_k^{(j)}\|_{\infty} \leq C_{\text{Gev}}(T, R) R^j j!^{\alpha},$$

for some constant $R > 0$.

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for some constant $R > 0$.

Moreover, R is related to the exponential decreasing of M_k (i.e. the constant K). We also want M_k to be of exponential type $T/2$, hence applying the Paley-Wiener Theorem, it is equivalent to saying that G_k has to be **of compact support** $[-T/2, T/2]$.

Link with Gevrey functions (3)

The function ψ_k will also be bounded by $C_{Gev}(T, R)$ and then the cost of the control is also bounded by $C_{Gev}(T, R)$. Hence, if we have to make all our possible to obtain some constant $C_{Gev}(T, R)$ which is **as small as possible**. We replace $G_k(-i\lambda_k) = 1$ by the condition $\int |G_k| = 1$ (and some suitable inequality on $G_k(i\lambda_k)$).

Link with Gevrey functions (3)

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Main issue

Bound from above the cost of the control is closely related to the following problem: given some $T > 0$, construct a Gevrey function G of order α , with support equal to $[-T/2, T/2]$, verifying $\int |G| = 1$, with imposed coefficient R appearing in the growth of the derivative and minimizing the quantity $C_{Gev}(T, R)$.

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The cost of fast controls for the fractional heat equation (1)

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Some notations $f(x) \lesssim g(x)$ ($x \in \mathcal{S}$): there exists $C > 0$ independent of x (might depend on other parameters) such that for every $x \in \mathcal{S}$,

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$f(x) \lesssim g(x, A^+)$: for every $K > A$, there exists a constant $C(K)$ such that

$$|f(x)| \leq C(K)g(x, K).$$

($C(K)$ might explode when $K \rightarrow A^+$)

The cost of fast controls for the fractional heat equation (2)

We denote by

$$\beta_+(\alpha) := \limsup_{T \rightarrow 0} T^{\frac{1}{\alpha-1}} \frac{\ln(C_H(T, L, \alpha))}{L^{\frac{\alpha}{\alpha-1}}},$$

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$\beta_-(L, 2) > 0$ (Guichal'85) and $\beta_+(L, 2) < \infty$ (Seidman'84), i.e.

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$\beta_-(2) \geq 1/4$ (Miller'04) and $\beta_+(2) \leq 3/4$ (Tenenbaum-Tucsnak'07). For $\alpha \geq 2$, precise estimates of $\beta_+(\alpha)$ in Lissy'14 (SICON).

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Natural conjecture

$\alpha_+(2) = 1/4 = \alpha_-(2)$, i.e. for T small $C_H(T, L, 2) \simeq e^{(L^2/4)^+/T}$.

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A new lower bound (1)

This natural conjecture is false!

Theorem (Lissy'15, JDE)

$$\beta_-(\alpha) \gtrsim \frac{2^{\frac{1}{\alpha-1}}(\alpha-1)}{(\alpha \sin(\frac{\pi}{\alpha}))^{\frac{\alpha}{\alpha-1}}}.$$

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Sketch of the proof

To simplify we restrict to the case $\alpha = 2$. We use a method introduced in Coron-Guerrero'05, based on the moment method and some tools from complex analysis. Also used in Lissy'15 (transport-diffusion), in Lissy-Gueye'16 (degenerate transport-diffusion) and in Lissy'16 (minimal time of control for parabolic systems).

We consider an optimal control u associated to the first eigenfunction $\sin(\pi x/L)$, which verifies

$$\|u\|_{L^2(0,L)} \leq C_H(T, L, 2) \|y^0\|_{H^{-1}(0,L)} \leq CC_H(T, L, 2) L^{3/2}.$$

A new lower bound (2)

By definition the control u has to solve to moment problem so we have

$$\frac{k\pi}{L} \int_0^T u(t) \exp\left(\frac{k^2\pi^2}{L^2}t\right) dt = - \int_0^L \sin\left(\frac{\pi}{L}\right) \sin\left(\frac{k\pi}{L}\right) dx.$$

Let us define the Fourier transform of u given by

$$v(z) := \int_{-T/2}^{T/2} u\left(t + \frac{T}{2}\right) \exp(-izt) dt.$$

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$$v(z) := \int_{-T/2}^{T/2} u\left(t + \frac{T}{2}\right) \exp(-izt) dt.$$

Let us consider some numerical parameter $\beta > 0$ to be chosen later. We introduce

$$f(z) := v\left(\frac{z - i\beta L^2}{T^2}\right).$$

It is easy to see that

$$|f(z)| \leq CC_H(T, L, 2) \sqrt{T} \exp\left(\frac{|\operatorname{Im}(z) - \beta L^2|}{2T}\right) L^{3/2}.$$

A new lower bound (3)

One has, for $k \in \mathbb{N}$ and $k > 1$,

$$f(b_k) = 0,$$

with

$$b_k := i \left(L^2 \beta + \frac{T^2 k^2 \pi^2}{L^2} \right).$$

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We also have

$$f(b_1) = -\frac{L^2}{2\pi} \exp\left(-\frac{\pi^2 T}{2L^2}\right),$$

with

$$b_1 := i \left(L^2 \beta + \frac{T^2 \pi^2}{L^2} \right).$$

A new lower bound (4)

We have the following equality, for every z such that $\text{Im}(z) > 0$:

$$\ln(|f(z)|) = \sum_1^{\infty} \ln\left(\frac{|z - a_l|}{|z - \bar{a}_l|}\right) + \sigma x_2 + \frac{x_2}{\pi} \int_{\mathbb{R}} \frac{\ln(|f(\tau)|)}{|\tau - z|^2} d\tau,$$

where the a_k are all the roots of f of positive imaginary part and σ is the type of f , which verifies

$$\sigma \leq \frac{1}{2T}.$$

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We apply this equality at point b_1 , we obtain

$$\ln(|f(b_1)|) \leq \sum_1^{\infty} \ln\left(\frac{|b_1 - a_l|}{|b_1 - \bar{a}_l|}\right) + \frac{L^2\beta}{2T} + \frac{T\pi^2}{2L^2} + \frac{|b_1|}{\pi} \int_{\mathbb{R}} \frac{\ln(|f(\tau)|)}{\tau^2 + |b_1|^2} d\tau.$$

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Let us study the right-hand side of this equality.

First term of the right-hand side: We study

$$I := \sum_{l=1}^{\infty} \ln\left(\frac{|b_1 - a_l|}{|b_1 - \bar{a}_l|}\right).$$

A new lower bound (5)

It is easy to prove that

$$\begin{aligned} I &\leq \sum_2^{\infty} \ln \left(\frac{|b_1 - b_l|}{|b_1 - \bar{b}_l|} \right) = \sum_2^{\infty} \ln \left(\frac{(k^2 - 1)T^2\pi^2/L^2}{2L^2\beta + (k^2 + 1)T^2\pi^2/L^2} \right) \\ &\leq \int_2^{\infty} \ln \left(\frac{x^2 T^2 \pi^2 / (2\beta L^4)}{1 + x^2 T^2 \pi^2 / (2\beta L^4)} \right) dx. \end{aligned}$$

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After some computations we obtain

$$\sum_1^{\infty} \ln \left(\frac{|b_1 - a_l|}{|b_1 - \bar{a}_l|} \right) \leq 2 \ln \left(1 + \frac{2\beta L^4}{(2\pi)^2 T^2} \right) - \frac{L^2(2\beta)^{\frac{1}{2}}}{T} + 2.$$

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Concerning the third term of the right-hand side, an easy changing of variables gives

$$|b_1| \int_{\mathbb{R}} \frac{d\tau}{\tau^2 + |b_1|^2} = \pi.$$

A new lower bound (6)

Hence, we deduce that

$$\frac{b_1}{\pi} \int_{\mathbb{R}} \frac{\ln |f(\tau)|}{\tau^2 + b_1^2} d\tau \leq \frac{\beta L^2}{2T} + \ln(CC_H(T, L)\sqrt{T}L^{3/2}).$$

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New conjecture

$\alpha_+(2) = 1/2 = \alpha_-(2)$, i.e. for T small enough $C_H(T, L, 2) \simeq e^{(L^2/2)^+/T}$.

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$\alpha_+(2) = 1/2 = \alpha_-(2)$, i.e. for T small enough $C_H(T, L, 2) \simeq e^{(L^2/2)^+/T}$.

In fact, this conjecture is **natural** if we look at the computations of Tenenbaum-Tucsna'07.

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Digression: the multiplier of Tenenbaum and Tucsnaak (1)

Let $\nu > 0$ et $\beta > 0$ two parameters We call

$$\sigma_\nu(t) := e^{-\frac{\nu}{1-t^2}},$$

extended to 0 outside $(-1, 1)$. We set

$$H_\beta(z) := C_\nu \int_{-1}^1 \sigma_\nu(t) e^{-i\beta tz} dt,$$

where

$$C_\nu := 1/\|\sigma_\nu\|_1.$$

Digression: the multiplier of Tenenbaum and Tucsnak (2)

This multiplier verifies

Lemme

$$H_\beta(0) = 1,$$

$$H_\beta(ix) \gtrsim \frac{e^{\beta|x|/(2\sqrt{\nu+1})}}{\sqrt{\nu+1}},$$

$$|H_\beta(z)| \leq e^{\beta|\operatorname{Im}(z)|}$$

$$H_\beta(x) \lesssim \sqrt{\nu+1} e^{3\nu/4 - (\pi+\delta/2)\sqrt{|x|}}.$$

A remarkable point is that this is actually the multiplier that gives the **best known result** for estimation of the cost of the control for the heat equation!

Main estimates

Proposition

Let $(a_k)_{k \geq 0}$ be a decreasing sequence of positive numbers such that

$$a := \sum_k a_k < \infty.$$

Then, there exists a nonnegative function u with compact support included in $[-a, a]$ verifying

$$\int_{-a}^a u = 1, \quad u(0) \leq \frac{1}{2a_0},$$

u is even, u is increasing on $[-a, 0]$,

such that for every $j \in \mathbb{N}$, one has

$$\|u^{(j)}\|_\infty \leq \frac{1}{\prod_{i=0}^j a_i}.$$

Idea of the proof

For every $b > 0$ we call

$$H_b := \frac{1_{[-b,b]}}{2b}.$$

Let us remark that

$$\int_{\mathbb{R}} H_b = 1$$

H_b is even.

Idea of the proof

For every $b > 0$ we call

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Let us remark that

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H_b is even.

We then consider

$$u_n := H_{a_0} * H_{a_1} * \cdots * H_{a_n},$$

where $*$ represents the convolution product. u_n is of class C^{n-1} with support included in $[-\sum_1^n a_i, \sum_1^n a_i]$. Moreover we can prove

$$\|u_n^{(j)}\|_{\infty} \leq \frac{1}{\prod_{i=0}^j a_i}.$$

Idea of the proof (2)

Let us also remark that u_n is even and verifies

$$\int_{-a}^a u_n(x) dx = \int H_{a_1} \cdots \int H_{a_n} = 1,$$

moreover

$$u_n(0) \leq \frac{1}{2a_0}.$$

We can prove that u_n is increasing on $[-\sum_1^n a_i, 0]$.

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We conclude as by letting $n \rightarrow \infty$, u being the limit (that exists) of the u_n .

An related Optimization Problem (1)

Minimizing $C_{Gev}(T, R)$ in our can be reformulated as follows. Let us set

$$\mathcal{A}_{adm}(a) := \{(a_k)_{k \in \mathbb{N}} \mid a_k > 0 \ \forall k, (a_k)_{k \in \mathbb{N}} \text{ is non-increasing, } \sum a_k = a\}.$$

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Then we are interested in

$$\inf_{(a_k) \in \mathcal{A}_{adm}(a)} \sup_{j \in \mathbb{N}} \prod_{i=0}^j \left(\frac{\nu^{\alpha-1}}{(i+1)^\alpha a_i} \right),$$

for some large enough (compared to a) parameter $\nu > 0$ to be chosen later. This problem seems quite difficult.

As a toy model, we propose to investigate the behavior of

$$\prod_{i=0}^{\infty} \left(\frac{(i+1)^\alpha a_i}{\nu^{\alpha-1}} \right)$$

on the set \mathcal{A}_{adm} . Are there **critical points**?

Let

$$f((a_k)) := \sum_{k=0}^{\infty} \ln \left(\frac{(k+1)^\alpha a_k}{\nu^{\alpha-1}} \right).$$

An related Optimization Problem (2)

One has

$$\frac{\partial f}{\partial a_i}((a_k)) = \frac{1}{a_k}.$$

Let

$$g((a_k)) := \sum_{k=0}^{\infty} a_k.$$

One has

$$\frac{\partial g}{\partial a_i}((a_k)) = 1.$$

We want to study f under the constraint $g((a_k)) = a$ for every $j \in \mathbb{N}$ (the constraint $a_k > 0$ can be forgotten here). We also do not need here to use that we want $(a_k)_{k \in \mathbb{N}}$ to be non-increasing.

Let $\lambda \in \mathbb{R}$ and $(\mu_j)_{j \in \mathbb{N}}$, we consider the Lagrangian

$$\mathcal{L}((a_k)) := f((a_k)) - \lambda g((a_k)).$$

An related Optimization Problem (3)

We remark that for every $j \in \mathbb{N}$, we have $\frac{\partial \mathcal{L}}{\partial a_j} = 0$ if and only if $a_j = \lambda$.
In contradiction with constraint $g((a_k)) = a$

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$$\begin{cases} a_k &= \frac{1}{\nu} & \text{if } k \leq \lfloor \nu \rfloor - 1, \\ a_k &= \frac{\nu}{(1+k)^\alpha} & \text{if } k \geq \lfloor \nu \rfloor, \end{cases}$$

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We call σ_ν the corresponding function constructed with the previous construction, its support is denoted a_ν and tends to $\alpha/(\alpha - 1)$ as $\nu \rightarrow \infty$.

Proposition

$$\|\sigma_\nu^{(j)}\|_\infty \lesssim \frac{e^{\alpha\nu} (j!)^\alpha}{\nu^{(\alpha-1)j}}, \quad j \in \mathbb{N}.$$

The multiplier

We have the following estimates:

We then set the multiplier

$$H_\beta(z) := \int_{-a_\nu}^{a_\nu} \sigma_\nu(t) e^{-i\beta tz} dt,$$

which will be our multiplier (up to some homothety). We have the following properties:

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Lemma

For every $\delta > 0$ small enough, one has

$$H_\beta(0) = 1, \tag{1}$$

$$|H_\beta(z)| \leq e^{a_\nu \beta |Im(z)|}, \tag{2}$$

$$|H_\beta(x)| \lesssim e^{\alpha \nu} e^{-\alpha(\beta \nu^{\alpha-1} |x|)^{1/\alpha} + \delta |x|^{1/\alpha}}, \quad x \in \mathbb{R}. \tag{3}$$

$$|H_\beta(ix)| \gtrsim e^{\frac{\beta x}{4\nu}}, \quad x > 0. \tag{4}$$

Main result

Adjusting the coefficients β and ν , (roughly, β as to be close to $T/4$ and ν should be chosen to absorb the bad growth of J_k), we obtain:

Theorem (Lissy'16, accepted in MCRF)

One has

$$\beta_+(\alpha) \leq \frac{1}{2(\alpha - 1)^{\frac{1}{\alpha-1}} \sin\left(\frac{\pi}{2\alpha}\right)^{\frac{\alpha}{\alpha-1}}}.$$

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Important point

- For $\alpha = 2$, $\beta_+(2) = 1$, worse that the result of Tenenbaum-Tucsnak'07 for the heat equation!
- But enables to treat much more general cases (notably all the possible cases of all controllable in arbitrary small time fractional heat or Schrödinger equations), under some modifications (eigenvalues in k^α for $\alpha > 1$). Hence, extends the results of Tenenbaum-Tucsnak '07 but also also the ones of Lissy'14 (SICON).

Perspectives

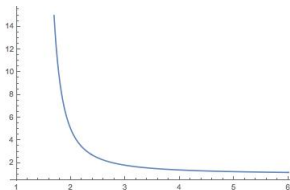


Figure: difference between the upper bound and the lower bound wrt α .

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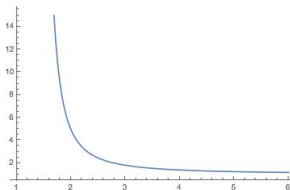


Figure: difference between the upper bound and the lower bound wrt α .

- Lower bound: study of first eigenfunction. Upper bound: linear combination of all modes. Does this explain that the lower bounds are far from the upper bounds?
- In the same spirit: is it possible to identify the “worst initial condition” for the cost of the control?
- Transmutation techniques as in Ervedoza-Zuazua'11.
- Improve the Bray-Mandelbrojt construction presented here.
- Improve the multiplier of Tenenbaum-Tuscnak'07.

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Thank you for your attention!