A SECOND ORDER ACCURACY IN TIME FOR A FULL DISCRETIZED TIME-DEPENDENT NAVIER-STOKES EQUATIONS BY A TWO-GRID SCHEME

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Abstract. We study a second-order two-grid scheme fully discrete in time and space for solving the Navier-Stokes equations. The two-grid strategy consists in discretizing, in the first step, the fully non-linear problem, in space on a coarse grid with mesh-size $H$ and time step $\Delta t$ and, in the second step, in discretizing the linearized problem around the velocity $u_H$ computed in the first step, in space on a fine grid with mesh-size $h$ and the same time step. The two-grid method has been applied for an analysis of a first order fully-discrete in time and space algorithm and we extend the method to the second order algorithm.

Keywords Two-grid scheme, Non-linear problem, Incompressible flow, Time and Space discretizations, Taylor-Hood finite element, Duality argument, “superconvergence”.

1. Introduction.

Let $\Omega$ be a bounded domain of $\mathbb{R}^2$ with a polygonal boundary $\partial \Omega$ and let $]0,T[$ be a given time-interval. Consider the following Navier-Stokes problem for an incompressible fluid

\[ \frac{\partial u}{\partial t}(x,t) - \nu \Delta u(x,t) + u(x,t) \cdot \nabla u(x,t) + \nabla p(x,t) = f(x,t) \text{ in } \Omega \times ]0,T[, \] (1.1)

with the incompressibility condition

\[ \text{div } u(x,t) = 0 \text{ in } \Omega \times ]0,T[, \] (1.2)

the homogeneous Dirichlet boundary condition

\[ u(x,t) = 0 \text{ on } \partial \Omega \times ]0,T[, \] (1.3)

and the initial condition

\[ u(x,0) = 0 \text{ in } \Omega, \] (1.4)

where $u$ and $p$ represent respectively the velocity and the pressure of the fluid. All the quantities are taken at the point $(x,t)$ where $x = (x_i)_{1 \leq i \leq 2} \in \mathbb{R}^2$ denotes the position and $t \in [0,T]$ the time. We suppose that the fluid density is a constant ($\rho = 1$); $f$ denotes the external forces applied to the fluid and $\nu$ is the viscosity. The notations $u \cdot \nabla u, \Delta u$ and $\text{div } u$ mean:

\[ u \cdot \nabla u = \sum_{i=1}^{2} u_i \frac{\partial u}{\partial x_i}, \Delta u = \sum_{i=1}^{2} \frac{\partial^2 u}{\partial x_i^2} \quad \text{and} \quad \text{div } u = \sum_{i=1}^{2} \frac{\partial u_i}{\partial x_i}. \]

The term $u \cdot \nabla u$ is the convection term and $\nu \Delta u$ is the diffusion one.

The purpose of this article is to solve by a second-order, in time and space, two-grid scheme, on a coarse grid and a fine grid, the non-stationary incompressible Navier-Stokes problem and to show that the two-grid algorithm’s global error is similar to the error of the direct resolution of the non-linear problem on a fine grid. The two-grid strategy is a general method for solving a non-linear Partial Differential Equation (PDE), depending or not in time, with solution $u$. This technique consists on what follows: In a first step, we discretize the fully non-linear PDE on a coarse grid of mesh-size $H$ and we compute an approximate solution $u_H$. Then, in a second step, we linearize the PDE around $u_H$ and we discretize
the linearized problem on a fine grid of mesh-size $h$; let $u_{h}^{in}$ be the corresponding solution. Then, under suitable assumptions, we can prove that if $h$, $H$ and the time step $\Delta t$ are well-chosen, the global error of the two-grid algorithm $\|u - u_{h}^{in}\|$ has the same order as the error $\|u - u_{h}\|$ that would have been obtained if the non-linear problem had been directly discretized on the fine grid.

Two-grid discretizations have been widely applied to linear and non-linear elliptic boundary value problems: J. Xu in [22], [23], [24] has pioneered their development. These methods have been extended to the steady Navier-Stokes equations, cf. for instance the work of W. Layton in [13], W. Layton & W. Lenferink in [14] and V. Girault & J.-L. Lions in [7]. Also, this method has been applied to the time-dependent Navier-Stokes problem, cf. V. Girault & J.-L. Lions [8] in which they analyze a semi-discrete algorithm, H. Abboud & T. Sayah in [2] and H. Abboud, V. Girault & T. Sayah in [3] for an analysis of a first order fully-discrete in time and space algorithm and in [1] for a numerical analysis of a second-order totally discrete in time and space scheme.

Setting $L_{0}^{2}(\Omega) = \{ q \in L^{2}(\Omega); \int_{\Omega} q \, dx = 0 \}$ and assuming that $f$ belongs to $L^{2}(0,T; H^{-1}(\Omega)^{2})$, it is well-known that (1.1)–(1.2) has the following variational formulation in $[0,T]$; Find $u(t) \in H_{0}^{1}(\Omega)^{2}$, such that in the sense of distributions on $[0,T]$,

$$\forall v \in H_{0}^{1}(\Omega)^{2}, \quad \frac{d}{dt}(u(t),v) + \nu(\nabla u(t), \nabla v) + (u(t) \cdot \nabla u(t), v) - (p(t), \text{div } v) = (f(t), v),$$

(1.5)

$$\forall q \in L_{0}^{2}(\Omega), (q, \text{div } u(t)) = 0,$$

(1.6)

and

$$u(0) = 0,$$

(1.7)

where $u(t) = u(x,t)$. Furthermore, this problem has one and only one solution $u$ in $L^{\infty}(0,T; L^{2}(\Omega)^{2}) \cap L^{2}(0,T; H^{1}(\Omega)^{2})$ and $p$ in the dual space of $W^{1,1}_{0}(0,T; L_{0}^{2}(\Omega))$ (see e.g. J.-L. Lions in [15] and O.A. Ladyzenskaya in [12]). In addition, we have the following regularity result:

**Theorem 1.1.** If $\Omega$ is convex and $f \in L^{2}(0,T; L^{2}(\Omega)^{2})$, then

$$u \in L^{\infty}(0,T; H^{1}(\Omega)^{2}) \cap L^{2}(0,T; H^{2}(\Omega)^{2}) \quad \text{and} \quad p \in L^{2}(0,T; H^{1}(\Omega)).$$

(1.8)

For discretizing (1.5)–(1.7), let $\eta > 0$ be a discretization parameter in space and for each $\eta$, let $T_{\eta}$ be a corresponding regular (or non-degenerate) family of triangulations of $\Omega$, consisting of triangles such that any two triangles are either disjoint or share a vertex or an entire side. For an arbitrary triangle $\kappa$, we denote by $\eta_{\kappa}$ the diameter of $\kappa$ and by $\rho_{\kappa}$ the diameter of the circle inscribed in $\kappa$. Then $\eta$ denotes the maximum of $\eta_{\kappa}$ and we assume that $T_{\eta}$ is regular in the sense of Ciarlet [6] there exists a constant $\sigma_{\kappa}$ independent of $\eta$ such that

$$\sup_{t \in T_{\eta}, \rho_{\kappa}} \frac{\eta_{\kappa}}{\rho_{\kappa}} = \sigma_{\kappa} \leq \sigma,$$

(1.9)

Let $X_{\eta}$ and $M_{\eta}$ be a “stable” pair of finite-element spaces for discretizing the velocity $u$ and the pressure $p$, stable in the sense that it satisfies a uniform discrete inf-sup condition: there exists a constant $\beta^{\star} \geq 0$, independent of $\eta$, such that

$$\forall q_{\eta} \in M_{\eta}, \quad \sup_{v_{\eta} \in X_{\eta}} \frac{1}{|v_{\eta}|_{H^{1}(\Omega)}} \int_{\Omega} q_{\eta} \text{div } v_{\eta} dx \geq \beta^{\star} \| q_{\eta} \|_{L^{2}(\Omega)}.$$

(1.10)

Let $P_{\kappa}$ denote the space of polynomials with total degree less than or equal to $\kappa$. For a second-order two-grid scheme, we choose the Taylor-Hood finite-element, where in each triangle $\kappa$, each component of the velocity is a polynomial of $P_{2}$ and the pressure $p$ is a polynomial of $P_{1}$. Therefore, the finite-element spaces are:

$$X_{\eta} = \left\{ v_{\eta} \in C^{0}(\overline{\Omega})^{2}; \forall \kappa \in T_{\eta}, v_{\eta|_{\kappa}} \in P_{2}^{2}, v_{\eta|_{\partial \Omega}} = 0 \right\},$$

(1.11)

$$M_{\eta} = \left\{ q_{\eta} \in C^{0}(\overline{\Omega})\cap L^{2}(\Omega); \forall \kappa \in T_{\eta}, q_{\eta|_{\kappa}} \in P_{1}, \int_{\Omega} q_{\eta} dx = 0 \right\}.$$

(1.12)
There exists an approximation operator $P_n \in \mathcal{L}(H^1_0(\Omega)^2; X_n)$ such that (see V. Girault and P.-A. Raviart in [9]):

$$\forall v \in H^1_0(\Omega)^2, \quad \forall q_n \in M_n, \quad \int_{\Omega} q_n \text{div}(P_n(v) - v) dx = 0,$$

(1.13)

and for $k = 0, 1$ or 2,

$$\forall v \in [H^{1+k}(\Omega) \cap \mathcal{H}_V^1(\Omega)]^2, \quad \| P_n(v) - v \|_{L^2(\Omega)} \leq C \eta^{1+k} |v|_{H^{1+k}(\Omega)},$$

(1.14)

and for all $r \geq 2, k = 0, 1$ or 2,

$$\forall v \in [W^{1+k,r}(\Omega) \cap \mathcal{H}_V^1(\Omega)]^2, \quad |P_n(v) - v|_{W^{1+k,r}(\Omega)} \leq C r \eta^{k} |v|_{W^{1+k,r}(\Omega)}.$$  

(1.15)

In addition, as $M_n$ contains all polynomials of degree one, there exists an operator $r_n \in \mathcal{L}(L^2_0(\Omega); M_n)$, such that for any real number $s \in [0, 2]$,

$$\forall q \in H^s(\Omega) \cap L^2_0(\Omega), \quad \| r_n(q) - q \|_{L^2(\Omega)} \leq C \eta^s |q|_{H^s(\Omega)}.$$  

(1.16)

To discretize in time, we divide the interval $[0, T]$ into $N$ subintervals of equal length $k = \frac{T}{N}$, with grid-points $t^n = nk, 0 \leq n \leq N$.

With these spaces, we propose the following two-grid scheme for discretizing (1.5)–(1.7). We use two regular triangulations of $\Omega$ : a coarse triangulation $T_H$ and a fine one $T_h$, that for practical purposes, is a refinement of $T_H$. On each of these, we define the same stable pair of finite-element spaces, $(X_H, M_H)$ and $(X_h, M_h)$ such that $X_H \subset X_h$ and $M_H \subset M_h$. At each time step, we solve (1.17)–(1.18) and (1.19)–(1.20) below. The two-grid algorithm reads:

- **Step One** (non-linear problem on coarse grid): Knowing $u^{n-1}_h$ and $u^n_H$, find $(u^{n+1}_h, p^{n+1}_H)$ with values in $X_H \times M_H$, solution of

$$\forall v_H \in X_H, \quad \frac{1}{2\Delta t} (3u^{n+1}_H - 4u^n_H + u^{n-1}_H, v_H) + \nu(\nabla u^{n+1}_H, \nabla v_H) + (u^{n+1}_H \cdot \nabla u^{n+1}_H, v_H)$$

$$+ \frac{1}{2} (\text{div } u^{n+1}_H, u^{n+1}_H \cdot v_H) - (p^{n+1}_H, \text{div } v_H) = (f^{n+1}, v_H),$$

$$\forall q_H \in M_H, \quad (q_H, \text{div } u^{n+1}_H) = 0.$$  

(1.17)

(1.18)

- **Step Two** (linearized problem on fine grid): Knowing $(u^{n+1}_H, p^{n+1}_H)$, find $(u^{n+1}_h, p^{n+1}_h)$ with values in $X_h \times M_h$, solution of

$$\forall v_h \in X_h, \quad \frac{1}{2\Delta t} (3u^{n+1}_h - 4u^n_h + u^{n-1}_h, v_h) + \nu(\nabla u^{n+1}_h, \nabla v_h) + (u^{n+1}_h \cdot \nabla u^{n+1}_h, v_h)$$

$$- (p^{n+1}_h, \text{div } v_h) = (f^{n+1}, v_h),$$

$$\forall q_h \in M_h, \quad (q_h, \text{div } u^{n+1}_h) = 0.$$  

(1.19)

(1.20)

By assumption, $u^0_H = u^0_h = 0$ and $u^1_H$ and $u^1_h$ are computed by solving one iteration of an Euler scheme. In both (1.17) and (1.19), $f^{n+1}$ is a suitable approximation of $f$ at time $t^{n+1}$. The purpose of this two-grid algorithm is to reduce the time of computation for both velocity and pressure.

In the sequel, we shall take $(\Delta t)^2$ of the order of $H^3$: there exist constants $\alpha_1$ and $\alpha_2$ that do not depend on $H$ and $\Delta t$ such that

$$\alpha_1 H^3 \leq (\Delta t)^2 \leq \alpha_2 H^3.$$  

The remainder of this article is organized as follows: In Section 2, we present some conventions and notations that will be used throughout the article. In Section 3, we present a first error estimate for the fully-discrete Step One, then in section 4 we establish a duality argument based on the backward semi-discrete Stokes system and we derive some uniform bounds that allow us to prove the Stokes problem’s error estimate in $L^2(\Omega \times [0, T])^2$, then we apply it to the Navier-Stokes problem. We also prove a “superconvergence” result for the non-linear part. Finally, the pressure is estimated in section 5 and the error estimation for the solution of Step Two is studied in section 6.
2. Preliminaries.

To begin with, we present some conventions and notations that will be used throughout the article. As usual, for handling time-dependent problems, it is convenient to consider functions defined on a time interval \([a, b]\) with values in a functional space, say \(X\) (cf. Lions and Magenes [16]). More precisely, let \(\| \cdot \|_X\) denote the norm of \(X\); then for any \(r, 1 \leq r \leq \infty\), we define

\[
L^r(a, b; X) = \left\{ f \text{ measurable in } [a, b]: \left( \int_a^b \| f(t) \|_X^r \, dt \right)^{1/r} < \infty \right\}
\]

equipped with the norm

\[
\| f \|_{L^r(a, b; X)} = \left( \int_a^b \| f(t) \|_X^r \, dt \right)^{1/r},
\]

with the usual modifications if \(r = \infty\). It is a Banach space if \(X\) is a Banach space.

Let \((k_1, k_2)\) denote a pair of non-negative integers, set \(|k| = k_1 + k_2\) and define the partial derivative \(\partial^k\) by \(\partial^k v = \frac{\partial^{|k|} v}{\partial x_1^{k_1} \partial x_2^{k_2}}\). Here \(X\) is usually a Sobolev space, such as (cf. Adams [4] or Nečas [17]): for any non-negative integer \(m\) and number \(r \geq 1\),

\[
W^{m, r}(\Omega) = \{ v \in L^r(\Omega); \partial^k v \in L^r(\Omega), \forall |k| \leq m \}.
\]

This space is equipped with the seminorm

\[
|v|_{W^{m, r}(\Omega)} = \left[ \sum_{|k|=m} \int_{\Omega} |\partial^k v|^r \, dx \right]^{1/r},
\]

and is a Banach space for the norm

\[
\| v \|_{W^{m, r}(\Omega)} = \left[ \sum_{0 \leq |k| \leq m} \| v \|_{W^{k, r}(\Omega)}^r \right]^{1/r},
\]

with the usual extension when \(r = \infty\). When \(r = 2\), this space is the Hilbert space \(H^m(\Omega)\). In particular, the scalar product of \(L^2(\Omega)\) is denoted by \((\cdot, \cdot)\). Similarly, \(L^2(a, b; H^m(\Omega))\) is a Hilbert space and in particular \(L^2(a, b; L^2(\Omega))\) coincides with \(L^2(\Omega \times [a, b])\).

For functions that vanish on the boundary, we recall Poincaré’s inequality: there exists a constant \(P\) such that

\[
\forall v \in H^1_0(\Omega), \| v \|_{L^2(\Omega)} \leq P |v|_{H^1(\Omega)}.
\]

More generally, recall the inequalities of Sobolev imbeddings in two dimensions: for each \(r \in [2, \infty]\), there exits a constant \(S_r\) such that

\[
\forall v \in H^1_0(\Omega), \| v \|_{L^r(\Omega)} \leq S_r |v|_{H^1(\Omega)},
\]

where

\[
|v|_{H^1(\Omega)} = \| \nabla v \|_{L^2(\Omega)}.
\]

When \(r = 2\), (2.2) reduces to Poincaré’s inequality and \(S_2\) is Poincaré’s constant. The case \(r = \infty\) is excluded and is replaced by: for any \(r > 2\), there exists a constant \(M_r\) such that

\[
\forall v \in W^{1,r}_0(\Omega), \| v \|_{L^\infty(\Omega)} \leq M_r |v|_{W^{1,r}(\Omega)}.
\]

We also have in dimension 2,

\[
\| g \|_{L^4(\Omega)} \leq 2^{1/4} \| g \|_{L^2(\Omega)}^{1/2} \| \nabla g \|_{L^2(\Omega)}^{1/2}.
\]

Owing to (2.1), we use the seminorm \(|\cdot|_{H^1(\Omega)}\) as a norm on \(H^1_0(\Omega)\) and we use it to define the norm of the dual space \(H^{-1}(\Omega)\) of \(H^1_0(\Omega)\):

\[
\| f \|_{H^{-1}(\Omega)} = \sup_{v \in H^1_0(\Omega)} \frac{(f, v)}{|v|_{H^1(\Omega)}},
\]
where $\langle \cdot, \cdot \rangle$ denotes the duality pairing between $H^{-1}(\Omega)$ and $H_0^1(\Omega)$. Also, we recall the spaces we introduced at the beginning:

$$V = \{ v \in H_0^1(\Omega)^2; \text{div}\,v = 0 \text{ in } \Omega \} \quad \text{and} \quad L_0^2(\Omega) = \{ q \in L^2(\Omega); \int_{\Omega} q\,dx = 0 \},$$

and the orthogonal complement of $V$ in $H_0^1(\Omega)^2$:

$$V^\perp = \{ v \in H_0^1(\Omega)^2; \forall w \in V, (\nabla v, \nabla w) = 0 \}.$$

The results of this article are based on the identity:

$$2(a^{n+1} + 3a^{n+1} - 4a^n + a^{n-1}) = |a^{n+1}|^2 + |2a^{n+1} - a^n|^2 + |a^n|^2 - 2a^n - a^{n-1}|^2, \quad (2.6)$$

where

$$\delta^2 a^n = a^{n+1} - 2a^n + a^{n-1}. \quad (2.7)$$

3. Error estimates for the solution of Step One

The results in this paragraph are written for the non-linear scheme (1.17)–(1.18).

To simplify, we denote by $\eta$ the mesh parameter. First of all, we prove the existence and the uniqueness of the solution of (1.17)–(1.18).

**Lemma 3.1. (Stability)** Let $u_{\eta}^{n+1}$ be a solution of (1.17)–(1.18) with the initial data $u_0$ and $u_1$ $\in V_\eta$:

We have

$$\sup_{2 \leq n \leq N} \| u_{\eta}^n \|_{L^2(\Omega)} + \sup_{2 \leq n \leq N} \| 2u_{\eta}^n - u_{\eta}^{n-1} \|_{L^2(\Omega)} + \sqrt{2}\nu (\sum_{n=2}^{N} \Delta t \| \nabla u_{\eta}^n \|_{L^2(\Omega)} )^{1/2}$$

$$+ \left( \sum_{n=1}^{N-1} \| \delta^2 u_{\eta}^n \|_{L^2(\Omega)} \right)^{1/2} \leq C \left( \frac{2\nu}{\nu} \sum_{n=2}^{N} \Delta t \| f^n \|_{L^2(\Omega)} + \| u_{\eta}^1 \|_{L^2(\Omega)} + \| 2u_{\eta}^1 - u_0 \|_{L^2(\Omega)} \right)^{1/2}.$$

**Proof.** We take the scalar product of (1.17) by $4\Delta tu_{\eta}^{n+1}$, use (2.6) and sum the result over $1 \leq n \leq m-1$. \hfill $\square$

The stability of (1.17)–(1.18) results from the following a priori estimation:

**Lemma 3.2. (Uniqueness)** The scheme (1.17)–(1.18) has a solution for all $\nu > 0$, all initial data $u_{\eta}^0, u_{\eta}^1 \in V_\eta$ and for all data $f \in C^0([0,T]; L^2(\Omega)^2)$. The solution is unique for $\Delta t$ sufficiently small.

**Proof.** For all $1 \leq n \leq N-1$, the problem (1.17)–(1.18) is a square system of algebraic non-linear equations in finite dimension. Due to the anti-symmetrisation of the non-linear term, we prove, by the theorem of the saddle point of Brouwer and the inf-sup condition, that for all $1 \leq n \leq N-1$, the problem has at least a solution $(u_{\eta}^n, p_{\eta}^n)$. For the unicity, we consider two solutions $(u_{\eta}^{(1)}, p_{\eta}^{(1)})$ and $(u_{\eta}^{(2)}, p_{\eta}^{(2)})$. Their difference $(w_{\eta}^n, p_{\eta}^n)$ satisfies:

$$\forall v_\eta \in V_\eta, \quad \frac{1}{2\Delta t} \left( 3w_{\eta}^{n+1} - 4w_{\eta}^n + w_{\eta}^{n-1}, v_\eta \right) + \nu(\nabla w_{\eta}^{n+1}, \nabla v_\eta) + (w_{\eta}^{n+1}, \nabla u_{\eta}^{(1)n+1}, v_\eta)$$

$$+ (w_{\eta}^{(2)n+1}, v_\eta) + \frac{1}{2}(\text{div}\,w_{\eta}^{n+1}, u_{\eta}^{(1)n+1}, v_\eta) + \frac{1}{2}(\text{div}\,w_{\eta}^{(2)n+1}, w_{\eta}^{n+1}, v_\eta) = 0.$$

By using the identity (2.6) and choosing $v_\eta = w_{\eta}^{n+1}$, we obtain

$$\frac{1}{4\Delta t} \left( \| w_{\eta}^{n+1} \|_{L^2(\Omega)}^2 + 2\| w_{\eta}^n - w_{\eta}^{n-1} \|_{L^2(\Omega)}^2 + \| \delta^2 w_{\eta}^n \|_{L^2(\Omega)}^2 - \| w_{\eta}^n - w_{\eta}^{n-1} \|_{L^2(\Omega)}^2 \right)$$

$$+ \nu|w_{\eta}^{n+1}|_{H^1(\Omega)}^2 - \| w_{\eta}^{n+1} \|_{H^1(\Omega)}^2 + 2\| w_{\eta}^{n+1} \|_{H^1(\Omega)}^2 + \| w_{\eta}^{n+1} \|_{L^2(\Omega)}^2 \| u_{\eta}^{(1)n+1} \|_{H^1(\Omega)}$$

$$- 2\| w_{\eta}^{n+1} \|_{L^2(\Omega)} \| w_{\eta}^{n+1} \|_{L^2(\Omega)} \leq 0.$$
Due to the fact that in finite dimension, all the norms are equivalent, summing the precedent inequality from \( n = 1 \) to \( m - 1 \), and using Lemma 3.1 and \( w_0^\eta = w_0^\eta = 0 \), we obtain
\[
\| w_\eta^m \|_{L^2(\Omega)}^2 + \nu \sum_{n=2}^{m} \Delta t |u_\eta^n|_{H^1(\Omega)}^2 + \sum_{n=1}^{m-1} \| \delta^2 w_\eta^n \|_{L^2(\Omega)}^2 + \| 2w_\eta^m - w_\eta^{m-1} \|_{L^2(\Omega)}^2 \leq C \Delta t \sum_{n=1}^{m} \| w_\eta^n \|_{L^2(\Omega)}^2 ,
\]
with a constant \( C \) that depends on \( \eta \) but does not depend on \( \Delta t \). For the last term of the sum of the right-hand side, we write:
\[
w_\eta^m = \delta^2 w_\eta^{m-1} + 2w_\eta^{m-1} - w_\eta^{m-2}.
\]
Then
\[
\| w_\eta^n \|_{L^2(\Omega)}^2 \leq 2 \left( \| \delta^2 w_\eta^{m-1} \|_{L^2(\Omega)}^2 + \| 2w_\eta^{m-1} - w_\eta^{m-2} \|_{L^2(\Omega)}^2 \right),
\]
and for \( \Delta t \) sufficiently small, the term
\[
2C \Delta t \left( \| \delta^2 w_\eta^{m-1} \|_{L^2(\Omega)}^2 + \| 2w_\eta^{m-1} - w_\eta^{m-2} \|_{L^2(\Omega)}^2 \right)
\]
can be absorbed by the term in the left-hand side of the inequality. Applying Gronwall’s lemma, we obtain \( w_\eta^0 = 0 \) then, the inf-sup condition implies \( p_\eta^0 = 0 \), \( 2 \leq n \leq N \). \( \square \)

In the next proposition, we will establish the error estimate for the solution computed by one iteration of Euler’s scheme \((u_\eta^1 - u(\Delta t), p_\eta^1 - p(\Delta t))\):

**Proposition 3.3.** Suppose that \( u'' \in C^0(0, T; L^2(\Omega))^2 \), \( u(\Delta t) \in H^2(\Omega)^2 \) and \( p(\Delta t) \in H^2(\Omega) \), the error of the solution computed by one iteration of Euler’s scheme satisfies the following estimations, for \( \Delta t \leq k_0 > 0 \) sufficiently small,
\[
\frac{1}{2} \left\| u_\eta^1 - u(\Delta t) \right\|_{L^2(\Omega)}^2 + \frac{\nu \Delta t}{2} \left\| u_\eta^1 - u(\Delta t) \right\|_{H^1(\Omega)}^2 \leq \frac{(\Delta t)^2}{4} \left\| u'' \right\|_{L^2(0, T; L^2(\Omega))^2}^2 + C(\Delta t)\eta^2 \left( \| u(\Delta t) \|_{H^2(\Omega)}^2 + \| p(\Delta t) \|_{H^2(\Omega)}^2 \right) + C\eta^6 \| u(\Delta t) \|_{H^2(\Omega)},
\]
and
\[
(\Delta t)^{1/2} \left\| p(\Delta t) - p_\eta^1 \right\|_{L^2(\Omega)} \leq C \left( (\Delta t)^{3/2} + \eta^2 + \frac{\eta^3}{\sqrt{\Delta t}} \right).
\]

**Proof.** Due to the regularity assumption of \( u \), there exists \( \theta \in ]0, 1[ \) such that
\[
0 = u_0 = u(\Delta t) - (\Delta t)u'(\Delta t) + \frac{1}{2}(\Delta t)^2u''(\theta \Delta t),
\]
and \( u_\eta^1 \) satisfies the following error equation
\[
\forall v_\eta \in V_\eta, \frac{1}{\Delta t}(u_\eta^1 - u(\Delta t), v_\eta) + \nu(\nabla(u_\eta^1 - u(\Delta t)), \nabla v_\eta) = \frac{\Delta t}{2}(u''(\theta \Delta t), v_\eta) - (p(\Delta t) - r_p p(\Delta t), \div v_\eta) + (u(\Delta t) \cdot \nabla u(\Delta t) - u_\eta^1 \cdot \nabla u_\eta^1, v_\eta) - \frac{1}{2} \left( \div u_\eta^1, u_\eta^1 \cdot v_\eta \right).
\]
Setting \( v_\eta = v_\eta^1 = u_\eta^1 - P_n u(\Delta t) \) and \( \varphi_\eta = P_n u(\Delta t) - u(\Delta t) \), we obtain
\[
\frac{1}{\Delta t} \left\| v_\eta^1 \right\|_{L^2(\Omega)}^2 + \nu \left\| v_\eta^1 \right\|_{H^1(\Omega)}^2 = \frac{\Delta t}{2}(u''(\theta \Delta t), v_\eta^1) + (r_p p(\Delta t) - p(\Delta t), \div v_\eta^1) - (v_\eta^1 \cdot \nabla u_\eta^1, v_\eta^1)
\]

\[
- \frac{1}{2} (\div v_\eta^1, u_\eta^1 \cdot v_\eta^1) - (\varphi_\eta \cdot \nabla u_\eta^1, v_\eta^1) - \frac{1}{2} \left( \div \varphi_\eta^1, u_\eta^1 \cdot v_\eta^1 \right)
\]

\[
- (u(\Delta t) \cdot \nabla \varphi_\eta^1, v_\eta^1) - \frac{1}{\Delta t} (\varphi_\eta^1, v_\eta^1) - \nu(\nabla \varphi_\eta^1, \nabla v_\eta^1) .
\]
Then (3.2) follows readily by applying the error approximation of \( P_\eta \).

For the pressure, we have

\[
(r_\eta p(\Delta t) - p(\Delta t), \text{div } v_\eta) + (p_\eta^1 - r_\eta p(\Delta t), \text{div } v_\eta) = \frac{1}{\Delta t} (u_\eta^1 - u(\Delta t), v_\eta) + \nu (\nabla(u_\eta^1 - u(\Delta t)), \nabla v_\eta)
\]

\[
- \frac{\Delta t}{2} (u''(\Delta t), v_\eta) - (u(\Delta t) \cdot \nabla u(\Delta t) - u_\eta^1 \cdot \nabla u_\eta^1, v_\eta) + \frac{1}{2} (\text{div } u_\eta^1, u_\eta^1 \cdot v_\eta),
\]

and owing to the inf-sup condition (1.10), there exists \( v_\eta \in V_\eta^+ \) such that

\[
(p_\eta^1 - r_\eta p(\Delta t), \text{div } v_\eta) = \| p_\eta^1 - r_\eta p(\Delta t) \|^2_{L^2(\Omega)} \quad \text{and} \quad |v_\eta|_{H^1(\Omega)} \leq \frac{1}{\beta^*} \| p_\eta^1 - r_\eta p(\Delta t) \|_{L^2(\Omega)},
\]

with \( \beta^* > 0 \) independent of \( \eta \). Then, by applying (3.2), we obtain (3.3).

The next result, stated in Lemma 3.4, is a standard error estimate. We give the proof for the sake of completeness.

**Lemma 3.4.** Let \( X_\eta \) and \( M_\eta \) be defined by (1.11) and (1.12) and approximate \( f^{n+1} \) by \( f^{n+1} = f(t^{n+1}) \).

At each time step, (1.17)–(1.18) has a solution \( u_\eta^{n+1} \) and this solution is unique if \( \Delta t \) is sufficiently small.

Suppose that \( u \in L^2(0,T;H^1(\Omega)^2) \), \( u' \in L^2(0,T;H^2(\Omega)^2) \), \( u^{(3)} \in L^2(\Omega \times [0,T])^2 \) and \( p \in L^2(0,T;H^2(\Omega)) \), there exist a constant \( C \) which does not depend on \( \eta \) and \( \Delta t \) and a constant \( k_0 > 0 \) that does not depend on \( \eta \) such that, for all \( \Delta t \leq k_0 \),

\[
\sup_{1 \leq n \leq N} \| u_\eta^n - u(t^n) \|_{L^2(\Omega)} + \left( \sum_{n=1}^{N-1} \| \delta^2(u_\eta^n - u(t^n)) \|^2_{L^2(\Omega)} \right)^{1/2} + \sqrt{\nu} \left( \sum_{n=1}^{N-1} \Delta t|u_\eta^{n+1} - u(t^{n+1})|^2_{H^1(\Omega)} \right)^{1/2}
\]

\[
\leq C(\eta^2 + (\Delta t)^2).
\]

**Proof.** Setting \( v_\eta^n = u_\eta^n - P_\eta u(t^n) \) and \( \varphi_\eta^n = P_\eta(u(t^n) - u(t^n)) \), \( 0 \leq n \leq N \), we substruct (1.17) and (1.1) taken at \( t = t^{n+1} \) and by using the following second-order backward finite difference scheme

\[
\frac{\partial u}{\partial t}(t^{n+1}) = \frac{3u(t^{n+1}) - 4u(t^n) + u(t^{n-1})}{2\Delta t} + O((\Delta t)^2),
\]

we have

\[
\left| u'(t + \Delta t) - \frac{3u(t + \Delta t) - 4u(t) + u(t - \Delta t)}{2\Delta t} \right| \leq \frac{(\Delta t)^{3/2}}{2\sqrt{3}} \| u^{(3)} \|_{L^2(t-\Delta t,t+\Delta t)},
\]

by summing the result over \( 1 \leq n \leq m - 1 \), we obtain:

\[
\| v_\eta^n \|^2_{L^2(\Omega)} + 2\| v_\eta^n - v_\eta^{n-1} \|^2_{L^2(\Omega)} + \sum_{n=1}^{m-1} \| \delta^2 v_\eta^n \|^2_{L^2(\Omega)} + 4\nu \sum_{n=1}^{m-1} \Delta t |v_\eta^{n+1}|^2_{H^1(\Omega)}
\]

\[
\leq \left( \| v_\eta^n \|^2_{L^2(\Omega)} + 2\| v_\eta^n - v_\eta^{n-1} \|^2_{L^2(\Omega)} \right) + 2 \sum_{n=1}^{m-1} \left( 3\varphi_\eta^n - 4\varphi_\eta^{n-1} + \varphi_\eta^{n-1} \right) + 4\nu \sum_{n=1}^{m-1} \Delta t(\nabla \varphi_\eta^{n+1}, \nabla v_\eta^{n+1})
\]

\[
+ 4 \sum_{n=1}^{m-1} \Delta t(p(t^{n+1}) - r_\eta p(t^{n+1}), \text{div } v_\eta^{n+1}) + 4 \sum_{n=1}^{m-1} \Delta t(\Delta t)^{3/2} \| u^{(3)} \|^2_{L^2(t^{n-1},t^{n+1})} \| v_\eta^{n+1} \|^2_{L^2(\Omega)}
\]

\[
+ 4 \sum_{n=1}^{m-1} \Delta t(u(t^{n+1}) \cdot \nabla u(t^{n+1}) - u_\eta^{n+1} \cdot \nabla u_\eta^{n+1}, v_\eta^{n+1}) - \frac{1}{2} \sum_{n=1}^{m-1} \Delta t(\text{div } u_\eta^{n+1}, u_\eta^{n+1} \cdot v_\eta^{n+1})
\]

\[
+ 4 \sum_{n=1}^{m-1} \Delta t(u(t^{n+1}) \cdot \nabla u(t^{n+1}) - u_\eta^{n+1} \cdot \nabla u_\eta^{n+1}, v_\eta^{n+1}) - \frac{1}{2} \sum_{n=1}^{m-1} \Delta t(\text{div } u_\eta^{n+1}, u_\eta^{n+1} \cdot v_\eta^{n+1})
\]

\[
= P_\eta u'(t^{n+1}) - u'(t^{n+1}) + R_2.
\]
with

$$|R_2| \leq \frac{(\Delta t)^{3/2}}{2\sqrt{3}} \| P_\eta u^{(3)} - u^{(3)} \|_{L^2(t^{n-1}, t^{n+1})}.$$ 

Hence, by assuming that $P_\eta$ is stable in the norm $L^2$ (cf. Girault and Lions [8]), we have

$$|(trhs)_2| = \left| 4 \sum_{n=1}^{m-1} \Delta t \left( \frac{3\eta^{n+1} + 4\eta^n + \eta^{n-1}}{2\Delta t}, v^{n+1}_\eta \right) \right|$$

$$\leq C \eta^4 \sum_{n=2}^{\infty} |u'|_2^2 \leq C \eta^4 \sum_{n=2}^{\infty} |\nabla \phi|_H^2 + C \eta^4 \sum_{n=2}^{\infty} |\nabla \phi|_H^2.$$ 

The third term is bounded as follows:

$$|(trhs)_3| = \left| 4 \sum_{n=1}^{m-1} \Delta t (\nabla \phi^{n+1}, \nabla \phi^{n+1}) \right| \leq \frac{2C \nu^4 \eta^4}{\varepsilon_3} \| u \|_{L^2(0,T;H^2(\Omega^2))}^2 + 2 \varepsilon_3 \sum_{n=1}^{m-1} |\nabla \phi|_H^2.$$ 

For the pressure contribution, we have:

$$|(trhs)_4| = \left| 4 \sum_{n=1}^{m-1} \Delta t (p(t^{n+1}) - p(t^{n+1}), \nabla \phi^{n+1}) \right| \leq \frac{2C \nu^4 \eta^4}{\varepsilon_4} \| p \|_{L^2(0,T;H^2(\Omega^2))}^2 + 2 \varepsilon_4 \sum_{n=1}^{m-1} |\nabla \phi|_H^2.$$ 

The fifth term is treated as follows:

$$|(trhs)_5| = \left| 4 \sum_{n=1}^{m-1} \Delta t (\nabla \eta^{n+1}, \nabla \eta^{n+1}) \right| \leq \frac{(\Delta t)^{3/2}}{2\sqrt{3}} \| u \|_{L^2(t^{n-1}, t^{n+1})}^2 + \varepsilon_5 \sum_{n=1}^{m-1} |\nabla \phi|_H^2.$$ 

Let us consider now the non-linear terms, $(trhs)_6 + (trhs)_7$, which are treated like follows:

$$(-u(t^{n+1}) \cdot \nabla u(t^{n+1}) + \eta^{n+1}_\eta \cdot \nabla \eta^{n+1}_\eta, v^{n+1}_\eta) + \frac{1}{2} (\nabla \eta^{n+1}_\eta, u^{n+1}_\eta \cdot v^{n+1}_\eta)$$

$$= -(-\eta^{n+1}_\eta \cdot \nabla \eta^{n+1}_\eta, P_\eta u(t^{n+1})) - \frac{1}{2} (\nabla \eta^{n+1}_\eta, P_\eta u(t^{n+1}) \cdot v^{n+1}_\eta) + (\eta^{n+1}_\eta \cdot \nabla \eta^{n+1}_\eta, P_\eta u(t^{n+1}))$$

$$- \frac{1}{2} (\nabla \eta^{n+1}_\eta, P_\eta u(t^{n+1}) \cdot v^{n+1}_\eta) + (u(t^{n+1}) \cdot \nabla v^{n+1}_\eta, \eta^{n+1}_\eta).$$

The study of the three terms in the right-hand side of (3.11), denoted by $(trhs)_6, j, j = 1, 2, 3$, will end the proof. Setting

$$C_1 = \sup_n |u(t^n)|_{H^1(\Omega)},$$

applying on one hand

$$\int_\Omega \nabla (\eta^{n+1}_\eta - u(t^{n+1})) \nabla \varphi^{n+1} \eta \eta dx = -\int_\Omega (\eta^{n+1}_\eta - u(t^{n+1})) \nabla u(t^{n+1}) \cdot \varphi^{n+1} \eta dx$$

$$-\int_\Omega (\eta^{n+1}_\eta - u(t^{n+1})) \cdot \nabla \varphi^{n+1} \eta \cdot u(t^{n+1}) dx,$$

and on the other hand

$$ab \leq \frac{a^p}{p} + \frac{b^p}{p},$$

we have

$$|(trhs)_6| = \left| 4 \sum_{n=1}^{m-1} \Delta t \left( (-\eta^{n+1}_\eta \cdot \nabla \eta^{n+1}_\eta, P_\eta u(t^{n+1})), \frac{1}{2} (\nabla \eta^{n+1}_\eta, P_\eta u(t^{n+1}) \cdot v^{n+1}_\eta) \right) \right|$$

$$\leq 3S_4 C_1 \sqrt{2} \sum_{n=1}^{m-1} |\nabla \phi|_H^2 + \frac{9S_4 C_1 \varepsilon_6^{4/3}}{2\sqrt{2}} \sum_{n=1}^{m-1} |\nabla \phi|_H^2.$$
which means that

These equations are completed by initial conditions similar to the Navier-Stokes problem’s ones.

We suppose that there exist two constants \( \alpha, \beta \)

Finally, (3.7) follows by applying a triangular inequality and the

\[
\| u \|_{L^2(0,T;H^2(\Omega))} + \varepsilon \sum_{n=1}^{m-1} \Delta t |v^{n+1}_\eta|^2_{H^1(\Omega)} \]

such that

\[
\| (\tau_{rhs})_1 \| = 4 \sum_{n=1}^{m-1} \Delta t \left( \| \phi^{n+1}_\eta \cdot \nabla v^{n+1}_\eta, P_\eta u(t^{n+1}) \| + \frac{1}{2} \| \text{div} \phi^{n+1}_\eta, P_\eta u(t^{n+1}) \cdot v^{n+1}_\eta \| \right) \]

and

\[
\| (\tau_{rhs})_2 \| = 4 \sum_{n=1}^{m-1} \Delta t \left( \| u(t^{n+1}) \cdot \nabla v^{n+1}_\eta, \phi^{n+1}_\eta \| \right) \]

\[
\leq 3S_2^2CC_1 \left\{ \frac{\eta^4}{\varepsilon_7} \| u \|_{L^2(0,T;H^2(\Omega))}^2 + \varepsilon_7 \sum_{n=1}^{m-1} \Delta t |v^{n+1}_\eta|^2_{H^1(\Omega)} \right\},
\]

After a suitable choice of \( \varepsilon_1 \), (3.10) becomes

\[
\| v^{m}_\eta \|_{L^2(\Omega)}^2 + 2 \| v^{m}_\eta - v^{m-1}_\eta \|_{L^2(\Omega)}^2 + \sum_{n=1}^{m-1} \| \delta^2 v^{n}_\eta \|_{L^2(\Omega)}^2 + \nu \sum_{n=1}^{m-1} \Delta t |v^{n+1}_\eta|^2_{H^1(\Omega)} \leq \alpha (\Delta t)^4 + \beta \eta^4 + \xi \sum_{n=1}^{m-1} \Delta t |v^{n+1}_\eta|^2_{L^2(\Omega)},
\]

where \( \alpha, \beta \) and \( \xi \) are constants that do not depend on \( \eta \) and \( \Delta t \).

Then after applying Gronwall’s lemma and for \( \Delta t \) sufficiently small, the result follows from this inequality:

\[
\sup_{1 \leq n \leq N} \| v^{n}_\eta \|_{L^2(\Omega)}^2 \leq \frac{\left( \sum_{n=1}^{N-1} \| \delta^2 v^{n}_\eta \|_{L^2(\Omega)}^2 + \nu \sum_{n=1}^{N-1} \Delta t |v^{n+1}_\eta|^2_{H^1(\Omega)} \right)^{1/2}}{\alpha (\Delta t)^2 + \beta \eta^4}. \]  

Finally, (3.7) follows by applying a triangular inequality and the \( P_\eta \)’s properties.

**Remark 3.5.** We suppose that there exist two constants \( \alpha' \) and \( \gamma' > 0 \) that do not depend on \( \eta \) and \( \Delta t \) such that

\[
\alpha' \eta^3 \leq (\Delta t)^2 \leq \gamma' \eta^3,
\]

which means that \((\Delta t)^2 \) is of the same order of \( \eta^3 \).

### 4. Some error estimates for the Stokes problem

The error estimate of order two in \( L^2(\Omega \times [0,T])^2 \), that will be established in the next section, is based on a duality argument for the transient Stokes problem:

\[
\frac{\partial v}{\partial t}(x,t) - \nu \Delta v(x,t) + \nabla q(x,t) = g(x,t) \text{ in } \Omega \times [0,T],
\]

\[
\text{div } v(x,t) = 0 \text{ in } \Omega \times [0,T], \quad v(x,t) = 0 \text{ on } \partial \Omega \times [0,T], \quad v(x,0) = 0 \text{ in } \Omega.
\]

The fully-discrete scheme for (4.1)–(4.2) is: Find \( (v^{n+1}_\eta, q^{n+1}_\eta) \) with values in \( X_\eta \times M_\eta \), for each \( 1 \leq n \leq N-1 \), solution of:

\[
\forall \eta \in X_\eta, \quad \frac{1}{2\Delta t} (3v^{n+1}_\eta - 4v^{n}_\eta + v^{n-1}_\eta, z_\eta) + \nu (\nabla v^{n+1}_\eta, \nabla z_\eta) - (q^{n+1}_\eta, \text{div } z_\eta) = (g^{n+1}_\eta, z_\eta),
\]

\[
\forall \lambda_\eta \in M_\eta, \quad (\lambda_\eta, \text{div } v^{n+1}_\eta) = 0.
\]

These equations are completed by initial conditions similar to the Navier-Stokes problem’s ones.

This linear problem (4.3)–(4.4) has a unique solution, owing to the inf-sup condition (1.10), without
any restriction on $\Delta t$. This solution satisfies the following error estimates in norm $L^\infty(0, T; L^2(\Omega)^2)$ and $L^2(0, T; H^1(\Omega))$: We prove, first of all, that the initial value $v_0^\Delta$, as in the Navier-Stokes problem, satisfies:

If $v(\Delta t) \in H^3(\Omega)^2$, $q(\Delta t) \in H^2(\Omega)$ and $v'' \in C^0([0, T]; L^2(\Omega)^2)$, then

$$
\| v_n^\Delta - v(\Delta t) \|_{L^2(\Omega)}^2 + \nu \Delta t \| v_n^\Delta - v(\Delta t) \|_{H^1(\Omega)}^2 
\leq \frac{(\Delta t)^4}{2} \| v'' \|_{L^\infty(0, T; L^2(\Omega)^2)}^2 + C(\Delta t)\eta^4 \left( \| v(\Delta t) \|_{H^2(\Omega)}^2 + \| q(\Delta t) \|_{H^2(\Omega)}^2 \right) + C\eta^6 \| v(\Delta t) \|_{H^2(\Omega)}^2.
$$

Secondly, in the general case, we have the following result (the proof is similar to the one of Lemma 3.4, but simpler because of the absence of the convection term).

**Lemma 4.1.** Let $(v, q)$ and $(v_\eta^n, q_\eta^n)$ be the respective solution of (4.1)–(4.2) and (4.3)–(4.4). In addition to the preceding hypotheses, we suppose that $g$ is regular enough in space and in time, $v \in L^2(0, T; H^3(\Omega)^2)$, $v' \in L^2(0, T; H^2(\Omega)^2)$, $v^{(3)} \in L^2(\Omega \times [0, T])^2$ and $q \in L^2(0, T; H^2(\Omega))$. There exists a constant $C$ that does not depend on $\eta$ and $\Delta t$ such that

$$
\sup_{1 \leq n \leq N} \| v_\eta^n - v(t^n) \|_{L^2(\Omega)} + \sup_{1 \leq n \leq N} \| 2(v_\eta^n - v(t^n)) - (v_\eta^{n-1} - v(t^{n-1})) \|_{L^2(\Omega)} 
+ \left( \sum_{n=1}^{N-1} \| \partial^2(v_\eta^n - v(t^n)) \|_{L^2(\Omega)}^2 \right)^{1/2} + \sqrt{\left( \sum_{n=1}^{N-1} |\Delta t|_n |v_\eta^n - v(t^n)|_{H^1(\Omega)}^2 \right)^{1/2}} 
\leq C(\eta^2 + (\Delta t)^2).
$$

In addition, the solution $(v^{n+1}_\eta, q^{n+1}_\eta)$ of (4.3)–(4.4) satisfies an error estimate in $L^\infty(0, T; H^1(\Omega)^2)$. To simplify, we introduce the following notation

$$
\delta^1 a = \frac{3a^{n+1} - 4a^n + a^{n-1}}{2\Delta t}.
$$

The proof is based on the following Stokes projection: $\forall (u, p) \in V \times L^2_0(\Omega), S_\eta(u) \in V_\eta$ satisfies

$$
\forall v_\eta \in V_\eta, \quad \nu(\nabla(S_\eta(u) - u), \nabla v_\eta) = -(p, \text{div} v_\eta).
$$

The operator $S_\eta$ satisfies the following inequalities:

**Lemma 4.2.** Let $(u, p) \in V \times L^2_0(\Omega), S_\eta(u)$ defined by (4.8) satisfies

$$
|S_\eta(u) - u|_{H^1(\Omega)} \leq 2|p_\eta(u) - u|_{H^1(\Omega)} + \frac{1}{\nu} \| r_\eta(p) - p \|_{L^2(\Omega)}.
$$

If in addition $\Omega$ is convex, there exists a constant $C$ that does not depend on $\eta$ such that

$$
\| S_\eta(u) - u \|_{L^2(\Omega)} \leq C\eta(|S_\eta(u) - u|_{H^1(\Omega)} + \| r_\eta(p) - p \|_{L^2(\Omega)}).
$$

**Lemma 4.3.** In addition to the hypotheses of Lemma 4.1, suppose that $v' \in C^0(0, T; H^2(\Omega)^2)$, $v'' \in L^2(0, T; H^2(\Omega)^2)$, $v^{(3)} \in L^2(\Omega \times [0, T])^2$, $q' \in C^0(0, T; H^1(\Omega))$ and $q'' \in L^2(\Omega \times [0, T])$. Then, if $\Omega$ is convex, there exists a constant $C$ that does not depend on $\eta$ and $\Delta t$ such that

$$
\sup_{1 \leq n \leq N} \| v_\eta^n - v(t^n) \|_{H^1(\Omega)} + \sup_{1 \leq n \leq N-1} \| 2(v_\eta^{n+1} - v(t^{n+1})) - (v_\eta^n - v(t^n)) \|_{H^1(\Omega)} 
+ \left( \sum_{n=1}^{N-1} \| \delta^1(v_\eta^n - v(t^n)) \|_{L^2(\Omega)}^2 \right)^{1/2} + \sqrt{\left( \sum_{n=1}^{N-1} |\Delta t|_n |v_\eta^n - v(t^n)|_{H^1(\Omega)}^2 \right)^{1/2}} 
\leq C(\eta^2 + (\Delta t)^3/2 + \frac{\eta^3}{\sqrt{\Delta t}}).
$$
Proof. Setting \( \varphi(t) = v(t) - S_\eta v(t) \), \( \varphi^i = \varphi(t^i) \) and \( e^i = v^i - S_\eta v(t^i) \) and applying (3.9) to (4.3), we obtain
\[
\forall z_\eta \in V_\eta, \quad (\delta^1 e^i_\eta, z_\eta) + \nu (\nabla (\nabla^2 e^i_\eta), \nabla z_\eta) = (\delta^1 \varphi^i_\eta, z_\eta) + R_3, \tag{4.12}
\]
where
\[
|R_3| \leq \frac{(\Delta t)^{3/2}}{2\sqrt{3}} \| v^{(3)} \|_{L^2(\Omega)} \| z_\eta \|_{L^2(\Omega)}.
\]
Taking the scalar product by \( z_\eta = z^{n+1}_\eta = \frac{3w^{n+1}_\eta - 4w^n_\eta + e^{n-1}_\eta}{2\Delta t} \), summing over \( 1 \leq n \leq m - 1 \), and applying Jensen’s inequality, (4.12) becomes
\[
\frac{1}{2} \sum_{n=1}^{m-1} \Delta t \| z^{n+1}_\eta \|_{L^2(\Omega)}^2 + \frac{\nu}{4} \left( |e^{2n}_\eta|_{H^1(\Omega)}^2 + |2e^{n}_\eta - e^{n-1}_\eta|_{H^1(\Omega)}^2 + \sum_{n=1}^{m-1} |\delta^2 e^{n}_\eta|_{H^1(\Omega)}^2 \right)
\leq \frac{5\nu}{4} |e^{1n}_\eta|_{H^1(\Omega)}^2 + \frac{(\Delta t)^4}{3} \| v^{(3)} \|_{L^2(\Omega)}^2 + \sum_{n=1}^{m-1} \Delta t \| \delta^1 \varphi^n_\eta \|_{L^2(\Omega)}^2.
\tag{4.13}
\]
Then (4.11) follows readily by applying (4.5), (4.9) and (4.10). \( \square \)

The parabolic duality argument (cf. [21]) consists in defining the solution \( (w^{n-1}, \lambda^{n-1}) \) of the backward semi-discrete Stokes system of second order in time:
\[
\begin{align*}
-w^{n+1} - 4w^n + 3w^{n-1} &+ \nu \Delta w^{n-1} - \nabla \lambda^{n-1} = v^{n-1} - v(t^n) \quad \text{in} \quad \Omega, \quad 1 \leq n \leq N + 1, \tag{4.14}
\end{align*}
\]
\[
\begin{align*}
\text{div} \, w^{n-1} = 0 \quad &\text{in} \quad \Omega, \quad 1 \leq n \leq N + 1, \\
w^{n-1}|_{\partial \Omega} = 0, \quad &1 \leq n \leq N + 1, \\
w^{N+2} = 0, \quad &w^{N+1} = 0 \quad \text{in} \quad \Omega. \tag{4.15}
\end{align*}
\]
For each \( n, 0 \leq n \leq N \), the Stokes problem (4.14)–(4.17) has a unique solution \( w^n \in H_0^1(\Omega)^2, \lambda^n \in L^2(\Omega) \), (cf. [9], [20]).

The next lemma establishes basic estimates for the velocity \( w^n \) of the backward semi-discrete Stokes problem (4.14)–(4.17).

Lemma 4.4. Standard arguments give the uniform bounds:
\[
\sup_{0 \leq n \leq N} \| w^n \|_{L^2(\Omega)} + \frac{\nu}{1 \leq n \leq N+1} \| 2w^{n-1} - w^n \|_{L^2(\Omega)} + \sqrt{2\nu} \left( \sum_{n=0}^{N} \Delta t |w^{n}_\eta|_{H^1(\Omega)}^2 \right)^{1/2}
\leq \sum_{n=1}^{N+1} \| \delta^2 w^n \|_{L^2(\Omega)}^2 + \frac{2\nu}{\nu} \left( \sum_{n=0}^{N} \Delta t \| v(t^n) - v^n_\eta \|_{L^2(\Omega)}^2 \right)^{1/2},
\tag{4.18}
\]
where \( S_2 \) is the constant of Poincaré's inequality, and
\[
\sqrt{\frac{\nu}{2}} \sup_{0 \leq n \leq N} |w^n|_{H^1(\Omega)} + \sqrt{\frac{\nu}{2}} \left( \sum_{n=1}^{N+1} |\delta^2 w^n|_{H^1(\Omega)}^2 \right)^{1/2} + \sqrt{\frac{\nu}{2}} \sup_{0 \leq n \leq N} |2w^n - w^{n-1}|_{H^1(\Omega)}
\leq \left( \sum_{n=0}^{N} \Delta t \| v(t^n) - v^n_\eta \|_{L^2(\Omega)}^2 \right)^{1/2}.
\tag{4.19}
\]
If \( \Omega \) is convex, then \( \forall 0 \leq n \leq N, w^n \in H^2(\Omega)^2, \lambda^n \in H^1(\Omega) \) and (4.19) implies the uniform bound
\[
\left( \sum_{n=0}^{N} \Delta t \left( |w^n|_{H^1(\Omega)}^2 + |\lambda^n|_{H^2(\Omega)}^2 \right) \right)^{1/2} \leq C \left( \sum_{n=0}^{N} \Delta t \| v(t^n) - v^n_\eta \|_{L^2(\Omega)}^2 \right)^{1/2},
\tag{4.20}
\]
with a constant \( C \) independent of \( \Delta t \) and \( \eta \).
Proof. For the first inequality, we take the scalar product of (4.14) with \( z = 4\Delta tw^{n-1} \), and we use the incompressibility condition. Multiplying the result by \( \Delta t \), summing it over \( n \) from \( m+1 \) to \( N+1 \), and applying the Poincaré inequality, we obtain for any \( \varepsilon > 0 \)

\[
\| w^n \|_{L^2(\Omega)}^2 + 2\| w^{n+1} - w^n \|_{L^2(\Omega)}^2 + 4\nu \sum_{n=m}^{N} \Delta t |w^n|_{H^1(\Omega)}^2 + \sum_{n=m+1}^{N+1} \| \partial^2 w^n \|_{L^2(\Omega)}^2 \leq 2 \varepsilon \sum_{n=m}^{N} \| v(t^n) - v^n_{m} \|_{L^2(\Omega)}^2 + 2\varepsilon S_2 \sum_{n=m}^{N} \Delta t |w^n|_{H^1(\Omega)}^2,
\]

where \( S_2 \) is Poincaré’s constant. Then (4.18) follows after the suitable choice of \( \varepsilon = \frac{\nu}{S_2} \).

Similarly, for the second inequality, we take the scalar product of (4.14) with \( z = \frac{w^{n+1} - 4w^n + 3w^{n-1}}{2\Delta t} \), we multiply the equation by \( \Delta t \) and sum it over \( n \). We obtain (4.19) by choosing \( \varepsilon = \frac{1}{2\Delta t} \).

Now, we assume that \( \Omega \) is convex. Since (4.14)–(4.17) is a steady Stokes problem with right-hand side \( -\frac{w^{n+1} - 4w^n + 3w^{n-1}}{2\Delta t} + (v(t^n) - v^n_{m}) \), we have \( w^n \in H^2(\Omega)^2, \lambda^n \in H^1(\Omega) \) (cf. [10]) and (4.19) implies also the uniform bound (4.20).

\[\square\]

From now on, we assume that \( \Omega \) is convex. Using these inequalities, the next theorem establishes that the error satisfies an estimate of order two in \( L^2(\Omega \times [0, T]) \).

**Theorem 4.5.** If \( g \in L^2(\Omega \times [0, T]) \), \( v \in L^2(0, T; H^2(\Omega)^2) \), \( q \in L^2(0, T; H^2(\Omega)), v' \in L^2(0, T; H^2(\Omega)^2) \) and \( v^{(3)} \in L^2(\Omega \times [0, T]) \), then there exists a constant \( C \) that depends on the norm of \( v, v', v^{(3)} \) and \( q \), but not on \( \eta \) and \( \Delta t \) such that

\[
\left( \sum_{n=0}^{N} \Delta t \| v^n_{\eta} - v(t^n) \|_{L^2(\Omega)}^2 \right)^{1/2} \leq C \eta^3 + (\Delta t)^2 + \eta(\Delta t)^2. \tag{4.21}
\]

In particular, if (3.16) holds, then

\[
\left( \sum_{n=0}^{N} \Delta t \| v^n_{\eta} - v(t^n) \|_{L^2(\Omega)}^2 \right)^{1/2} \leq C \eta^3. \tag{4.22}
\]

Proof. Let \( e^{n-1} = v^n_{\eta} - v(t^{n-1}) \). Taking the scalar product of (4.14) by \( e^{n-1} \), summing over \( n \) form 1 to \( N+1 \) and applying a discrete integration by parts, we obtain

\[
\sum_{n=0}^{N} \Delta t \| e^n \|_{L^2(\Omega)}^2 = \sum_{n=1}^{N-1} \left\{ -\frac{1}{2} (3e^{n+1} - 4e^n + e^{n-1}, P_{\eta}w^{n+1}) - \nu \Delta t (\nabla P_{\eta}w^{n+1}, \nabla e^{n-1}) \right\} - \frac{1}{2} \sum_{n=1}^{N+1} (3e^{n+1} - 4e^n + e^{n-1}, w^{n+1} - P_{\eta}w^{n+1}) - \nu \sum_{n=1}^{N+1} \Delta t (\nabla (w^{n+1} - P_{\eta}w^{n+1}), \nabla e^{n-1}) \tag{4.23}
\]

\[
+ \sum_{n=1}^{N+1} \Delta t (\lambda^{n-1} - r_{\eta} \lambda^{n-1}, \text{div} e^{n-1}) - \left\{ \frac{3}{2} (w^{1}, e^{1}) + \nu \Delta t (|e^{1}|^2, \nabla P_{\eta}w^{1}) \right\}.
\]

Denote the terms in the right-hand side of (4.23) by \( (W_{RH})_j, j = 1, \ldots, 5 \). The first term is treated as...
Finally, the last term can be written as follows:

\[
|(W_{RH})_1| \leq \left| \sum_{n=1}^{N} \Delta t \left( q(t^{n+1}) - r_\eta q(t^n), \text{div}(P_\eta w^{n+1} - w^{n+1}) \right) \right| \\
+ \frac{P}{\sqrt{3}} (\Delta t)^2 \| v^{(3)} \|_{L^2(\Omega)}^2 \left( \sum_{n=1}^{N-1} \Delta t |P_\eta w^{n+1}|^2_{H^1(\Omega)} \right)^{1/2} \\
\leq C \eta^3 \| q \|_{L^2(0,T;H^1(\Omega))} + \frac{P}{\sqrt{3}} (\Delta t)^2 \| v^{(3)} \|_{L^2(\Omega)}^2 \left( \sum_{n=0}^{N} \Delta t \| e^n \|_{L^2(\Omega)}^2 \right)^{1/2}.
\]

The second term is bounded as follows:

\[
|(W_{RH})_2| \leq \left( \sum_{n=1}^{N} \Delta t \| \delta^1 e^n \|_{L^2(\Omega)}^2 \right)^{1/2} \left( \sum_{n=1}^{N} \Delta t \| w^{n+1} - P_\eta w^{n+1} \|_{L^2(\Omega)}^2 \right)^{1/2} \\
\leq C \eta^2 ((\Delta t)^{1/2} + \eta^2) \left( \sum_{n=0}^{N} \Delta t \| e^n \|_{L^2(\Omega)}^2 \right)^{1/2}.
\]

Owing to Lemma 4.1, the third and fourth terms can be bounded by:

\[
|(W_{RH})_3| \leq C \eta \left( \sum_{n=0}^{N} \Delta t |e^n|^2_{H^1(\Omega)} \right)^{1/2} \left( \sum_{n=0}^{N} \Delta t |w^n|^2_{H^2(\Omega)} \right)^{1/2} \\
\leq C \eta ((\Delta t)^2 + \eta^2) \left( \sum_{n=0}^{N} \Delta t \| e^n \|_{L^2(\Omega)}^2 \right)^{1/2},
\]

and

\[
|(W_{RH})_4| \leq C \eta ((\Delta t)^2 + \eta^2) \left( \sum_{n=0}^{N} \Delta t \| e^n \|_{L^2(\Omega)}^2 \right)^{1/2}.
\]

Finally, the last term can be written as follows:

\[
|(W_{RH})_5| = -\frac{3}{2} (\| w^1 - P_\eta w^1, e^1 \| - \frac{3}{2} (\| P_\eta w^1, e^1 \| + v \Delta t (\nabla e^1, \nabla P_\eta w^1) + \nu \Delta t (\nabla e^1, \nabla P_\eta w^1)) - \frac{\nu}{2} \Delta t (\nabla e^1, \nabla P_\eta w^1).
\]

Let us consider the terms between square brackets and write the error equation at time \( t^1 \) : there exists \( \theta \in [0,1] \) such that

\[
(e^1, P_\eta w^1) + \nu \Delta t (\nabla e^1, \nabla P_\eta w^1) = \Delta t (r_\eta q(\Delta t) - q(\Delta t), \text{div} P_\eta w^1) - \frac{(\Delta t)^2}{2} (\| u''(\theta \Delta t), P_\eta w^1),
\]

then

\[
\left| (e^1, P_\eta w^1) + \nu \Delta t (\nabla e^1, \nabla P_\eta w^1) \right| \leq C \left[ (\Delta t) \eta^2 |q(\Delta t)|_{H^2(\Omega)} + \frac{(\Delta t)^2}{2} \| u'' \|_{L^\infty(0,T;L^2(\Omega))} \right] \\
\left( \sum_{n=0}^{N} \Delta t \| e^n \|_{L^2(\Omega)}^2 \right)^{1/2}.
\]

The first and last parts of \((W_{RH})_5\) are bounded by using (4.5).
Substituting these inequalities into (4.23), we obtain (4.21). In addition, if (3.16) holds, then (4.21) implies (4.22). \(\square\)

Now, we split \( u_{n}^{\eta} - u(t^n) \) into a linear contribution, \( v_{n}^{\eta} = u(t^n) \), and a non-linear one \( u_{n}^{\eta} - v_{n}^{\eta} \). Here \( v_{n+1}^{\eta} \) is the solution of the Stokes problem (4.3)-(4.4) with \( g = f - u \cdot \nabla u \). Therefore, \( v = u \) and \( e_{n+1}^{\eta} \) solves the discrete problem \( \forall w_{\eta} \in V_{\eta}, \)

\[
\frac{3v_{n+1}^{\eta} - 4v_{n}^{\eta} + v_{n-1}^{\eta}}{2\Delta t} + \nu (\nabla v_{n+1}^{\eta}, \nabla w_{\eta}) - (q_{n+1}^{\eta}, \text{div} w_{\eta}) = (f(t_{n+1}) - u(t_{n+1}) \cdot \nabla u(t_{n+1}), w_{\eta}).
\]

Therefore, Theorem 4.5 gives
Corollary 4.6. Suppose that \( u \) satisfies the hypotheses on \( v \) in Theorem 4.5 and that \( f \in C^0([0, T]; L^2(\Omega)^2) \) then
\[
\left( \sum_{n=0}^{N} \Delta t \| v_n^m - u(t^n) \|_{L^2(\Omega)^2}^2 \right)^{1/2} \leq C(\eta^3 + (\Delta t)^2 + \eta(\Delta t)^2),
\]
with another constant \( C(f, u, p, \nu, T) \) that does not depend on \( \eta \) nor on \( \Delta t \).

Furthermore, if \( p' \) belongs to \( L^2(0, T; H^1(\Omega)) \), Lemma 4.3 implies that
\[
\sup_{0 \leq n \leq N} \| v_n^m - u(t^n) \|_{H^1(\Omega)} \leq C(\eta^2 + (\Delta t)^{3/2} + \eta^3 \sqrt{\Delta t}).
\]

On the other hand, we prove the following “superconvergence” result for the non-linear part.

Theorem 4.7. Under the assumptions of Corollary 4.6 and if \( p' \in L^2(0, T; H^1(\Omega)) \), \( u' \in L^2(0, T; H^1(\Omega)^2) \) and \( u \in L^\infty(0, T; W^{1,1}(\Omega)^2) \) then there exists a constant \( C \) that does not depend on \( \eta \) and \( \Delta t \), such that
\[
\sup_{0 \leq n \leq N} \| v_n^m - u_n^m \|_{L^2(\Omega)} + \sup_{1 \leq n \leq N} \| v_n^m - u_n^m - (v_{n-1}^m - u_{n-1}^m) \|_{L^2(\Omega)}
\]
\[
+ \left( \sum_{n=1}^{N-1} \| \delta^2(v_n^m - u_n^m) \|_{L^2(\Omega)}^2 \right)^{1/2} + \left( \sum_{n=0}^{N-1} \Delta t|v_{n+1}^m - v_{n+1}^m|_{H^1(\Omega)}^2 \right)^{1/2} \leq C(\eta^3 + (\Delta t)^2).
\]

Proof. In one hand, we take the difference between (4.24) and (1.17). We split the non-linear term as follows:
\[
u_n^{m+1} \cdot \nabla u_n^{m+1} + \frac{1}{2} \text{div} u_n^{m+1} u_n^{m+1} - u(t^{n+1}) \cdot \nabla u(t^{n+1})
\]
\[-\varphi_n^{m+1} \cdot \nabla u_n^{m+1} - \frac{1}{2} \text{div} \varphi_n^{m+1} u_n^{m+1} - \varphi_n^{m+1} \cdot \nabla \varphi_n^{m+1} - \frac{1}{2} \text{div} \varphi_n^{m+1} \varphi_n^{m+1}
\]
\[+ (v_n^{m+1} - u(t^{n+1})) \cdot \nabla (v_n^{m+1} - u(t^{n+1})) + \frac{1}{2} \text{div} (v_n^{m+1} - u(t^{n+1}))(v_n^{m+1} - u(t^{n+1}))
\]
\[+ (v_n^{m+1} - u(t^{n+1})) \cdot \nabla u(t^{n+1}) + \frac{1}{2} \text{div} (v_n^{m+1} - u(t^{n+1}))u(t^{n+1}) + u(t^{n+1}) \cdot \nabla (v_n^{m+1} - u(t^{n+1})).
\]

On the other hand, we multiply the resultant equation by \( \varphi_n^{m+1} \) and sum it over \( n = 1, \ldots, m-1 \). We obtain:
\[
\sum_{n=1}^{m-1} \left( \varphi_n^{m+1} \cdot \nabla u_n^{m+1} - 4 \varphi_n^{m} + \varphi_n^{m-1} \right) + \nu \sum_{n=1}^{m-1} \Delta t|\varphi_n^{m+1}|_{H^1(\Omega)}^2
\]
\[
= \sum_{n=1}^{m-1} \Delta t \left\{ \left(-\varphi_n^{m+1} \cdot \nabla u_n^{m+1}, \varphi_n^{m+1} \right) + \frac{1}{2} \left( \text{div} \varphi_n^{m+1} u_n^{m+1}, \varphi_n^{m+1} \right) \right\}
\]
\[+ \sum_{n=1}^{m-1} \Delta t \left\{ \left((v_n^{m+1} - u(t^{n+1})) \cdot \nabla (v_n^{m+1} - u(t^{n+1})), \varphi_n^{m+1} \right) + \frac{1}{2} \left( \text{div} (v_n^{m+1} - u(t^{n+1})), (v_n^{m+1} - u(t^{n+1})), \varphi_n^{m+1} \right) \right\}
\]
\[+ \sum_{n=1}^{m-1} \Delta t \left\{ \left((v_n^{m+1} - u(t^{n+1})) \cdot \nabla u(t^{n+1}), \varphi_n^{m+1} \right) + \frac{1}{2} \left( \text{div} (v_n^{m+1} - u(t^{n+1})), (v_n^{m+1} - u(t^{n+1})), \varphi_n^{m+1} \right) \right\}.\]

The left-hand side of (4.28) can be written as follows:
\[
\frac{1}{4} \| \varphi_n^{m} \|_{L^2(\Omega)}^2 + \frac{1}{4} \| \varphi_n^{m} \|_{L^2(\Omega)}^2 + \frac{1}{4} \| \varphi_n^{m-1} \|_{L^2(\Omega)}^2 - \frac{1}{4} \| \varphi_n^{m-1} \|_{L^2(\Omega)}^2 + \frac{1}{4} \| \varphi_n^{m} \|_{L^2(\Omega)}^2
\]
\[+ \frac{1}{4} \sum_{n=1}^{m-1} \| \delta^2 \varphi_n^{m} \|_{L^2(\Omega)}^2 + \nu \sum_{n=1}^{m-1} \Delta t|\varphi_n^{m+1}|_{H^1(\Omega)}^2.
\]

We note \( (UR1), \), \( i = 1, \ldots, 4 \), the terms in the right-hand side of (4.28). For the first term, setting \( C_1 = \sup_n \| u_n^m \|_{H^1(\Omega)} \), we can write
\[
\frac{1}{2} \left( \sqrt{\frac{1}{2} \varepsilon_1 + \frac{1/4 S 3/4}{8}} \right) \sum_{n=1}^{m-1} \Delta t|\varphi_n^{m+1}|_{H^1(\Omega)}^2 + \frac{1/4 S 3/4}{8} \sum_{n=1}^{m-1} \Delta t \| \varphi_n^{m+1} \|_{L^2(\Omega)}^2.\]
Setting $C_3 = \sup_n \| u(t^{n+1}) \|_{L^\infty(\Omega)}$ and due to Corollary 4.6, the second term is bounded as follows:

$$|(U_{RH})_2| \leq \frac{CC_3}{2 \varepsilon_3}(\eta^6 + (\Delta t)^4 + (\Delta t)^6 \eta^2) + \frac{C_3 \varepsilon_3}{2} \sum_{n=1}^{m-1} \Delta t |\varphi_{n+1}^{n+1}|^2_{H^1(\Omega)}.$$  

For the third term, we use Lemma 4.1 and (4.26) and we obtain:

$$|(U_{RH})_3| \leq \frac{CS^2}{2 \varepsilon_4}(\eta^8 + (\Delta t)^7 + (\Delta t)^5 \eta^4) + \frac{3S^2_4 \varepsilon_4}{4} \sum_{n=1}^{m-1} \Delta t |\varphi_{n+1}^{n+1}|^2_{H^1(\Omega)}.$$  

In order to bound the last term, we use the well-known formula (3.12):

$$((v_{n+1}^n - u(t^{n+1})) \cdot \nabla u(t^{n+1}), \varphi_{n+1}^{n+1}) + \frac{1}{2}(\text{div}(u_{n+1}^n - u(t^{n+1})), u(t^{n+1}) \cdot \varphi_{n+1}^{n+1})$$

$$= \frac{1}{2}((v_{n+1}^n - u(t^{n+1})) \cdot \nabla u(t^{n+1}), \varphi_{n+1}^{n+1}) - \frac{1}{2}((v_{n+1}^n - u(t^{n+1})) \cdot \nabla \varphi_{n+1}^{n+1}, u(t^{n+1})), \quad (4.29)$$

we set $C_2 = \sup_{1 \leq n \leq N} |u(t^{n+1})|_{W^{1,4}(\Omega)}$ and we obtain:

$$|(U_{RH})_4| \leq \frac{C(C_2 S_4 + C_3)}{4 \varepsilon_5}(\eta^6 + (\Delta t)^4 + \eta^2(\Delta t)^4) + \frac{(S_4 C_2 + C_3) \varepsilon_5}{4} \sum_{n=1}^{m-1} \Delta t |\varphi_{n+1}^{n+1}|^2_{H^1(\Omega)}.$$  

Finally, we still have to estimate $\varphi_{\eta}^1$:

$$\| \varphi_{\eta}^1 \|^2_{L^2(\Omega)} + \nu \Delta t |\varphi_{\eta}^1|^2_{H^1(\Omega)} = \Delta t \left|(u_{\eta}^1 \cdot \nabla u_{\eta}^1 - u(\Delta t) \cdot u(\Delta t), \varphi_{\eta}^1)\right|.$$  

The non-linear term is split as the general one. The first part is bounded by:

$$\frac{C_4}{2} \left\{ (\sqrt{2} \varepsilon_6 + \frac{2^{1/2} S_4 \varepsilon_2^{1/2}}{8}) \Delta t |\varphi_{\eta}^1|^2_{H^1(\Omega)} + \frac{\sqrt{2}}{\varepsilon_6} + \frac{2^{1/2} S_4}{8 \varepsilon_7^2} \Delta t \| \varphi_{\eta}^1 \|^2_{L^2(\Omega)} \right\},$$

and if $\Delta t$ is sufficiently small, these terms are absorbed by the left-hand side of (4.28). In the second part, we obtain:

$$\Delta t \| v_{\eta}^1 - u(t^1) \|^2_{L^2(\Omega)} \leq C(\eta^6 + (\Delta t)^4),$$

and in the third one:

$$\Delta t |v_{\eta}^1 - u(\Delta t)|_{H^1(\Omega)} \| v_{\eta}^1 - u(\Delta t) \|_{L^1(\Omega)} |\varphi_{\eta}^1|_{H^1(\Omega)}$$

$$\leq \frac{1}{\varepsilon_8} \Delta t |\varphi_{\eta}^1|^2_{H^1(\Omega)} + \frac{1}{\varepsilon_8} C(\eta^8 + \eta^6(\Delta t)^3/2 + \frac{\eta^6}{\sqrt{\Delta t}} + \eta^4(\Delta t)^{7/2}).$$

In the last part, we obtain:

$$\Delta t \| v_{\eta}^1 - u(t^1) \|^2_{L^2(\Omega)} \leq C(\eta^6 + (\Delta t)^4).$$

Then (4.27) follows readily by applying these results. \hfill \square

Combining Corollary 4.6 and Theorem 4.7, we obtain:

**Corollary 4.8.** **Under the assumptions of Theorem 4.7, there exists a constant $C$ that does not depend on $\eta$ and $\Delta t$, such that**

$$\left( \sum_{n=0}^{N} \Delta t \| u(t^n) - u_{\eta}^n \|^2_{L^2(\Omega)} \right)^{1/2} \leq C(\eta^3 + (\Delta t)^2), \quad (4.30)$$

**In particular, if (3.16) holds, then**

$$\left( \sum_{n=1}^{N-1} \Delta t \| u(t^{n+1}) - u_{\eta}^{n+1} \|^2_{L^2(\Omega)} \right)^{1/2} \leq C\eta^3. \quad (4.31)$$
The results of the preceding section allow one to establish an error estimate for the pressure. We start with a general bound.

**Lemma 5.1.** Under the assumptions of Lemma 3.4, let \((u(t^{n+1}), p(t^{n+1}))\) and \((u_\eta^{n+1}, p_\eta^{n+1})\) be the respective solution of (1.1)–(1.4) and (1.17)–(1.18). We have

\[
\begin{align*}
&\sum_{n=1}^{N-1} \Delta t \| p_\eta^{n+1} - r_\eta p(t^{n+1}) \|_{L^2(\Omega)}^2 \leq \frac{1}{\beta^*} \left\{ C_1(\eta^2 + (\Delta t)^2) + C_2(\Delta t)^2 \| u^{(3)} \|_{L^2(\Omega \times [0,T])}^2 \ight. \\
&\left. + C_3 \| p \|_{L^2(0,T; H^2(\Omega))} + S_2 \sum_{n=1}^{N} \Delta t \| \delta^1(u_\eta^n - u(t^n)) \|_{L^2(\Omega)}^2 \right\},
\end{align*}
\]

where \(\beta^*\) is the constant of the inf-sup condition (1.10) and the coefficients \(C_i, 1 \leq i \leq 3\), are independent of \(\eta\) and \(\Delta t\).

**Proof.** Let us substract the non-linear terms and set \(e_\eta^i = u_\eta^i - u(t^i)\). We obtain

\[
\begin{align*}
u(t^{n+1}) \cdot \nabla u(t^{n+1}) - u_\eta^{n+1} \cdot \nabla u_\eta^{n+1} - \frac{1}{2} \operatorname{div} u_\eta^{n+1} \cdot u_\eta^{n+1} &= -u(t^{n+1}) \cdot \nabla e_\eta^{n+1} - e_\eta^{n+1} \cdot \nabla u_\eta^{n+1} - \frac{1}{2} \operatorname{div} e_\eta^{n+1} \cdot u_\eta^{n+1}.
\end{align*}
\]

Then, for all \(w_\eta^n \in X_\eta\) and due to (3.9), we have

\[
\begin{align*}
&\sum_{n=1}^{N-1} \Delta t (p_\eta^{n+1} - r_\eta p(t^{n+1}), \operatorname{div} w_\eta^n) + \nu \sum_{n=1}^{N-1} \Delta t (\nabla e_\eta^{n+1}, \nabla w_\eta^n) \\
&+ \sum_{n=1}^{N-1} R_1 + \sum_{n=1}^{N-1} \Delta t (u(t^{n+1}) \cdot \nabla e_\eta^{n+1}, w_\eta^n) + \sum_{n=1}^{N-1} \Delta t \left\{ (e_\eta^{n+1} \cdot \nabla u_\eta^{n+1}, w_\eta^{n+1}) + \frac{1}{2} \operatorname{div} e_\eta^{n+1} u_\eta^{n+1}, w_\eta^{n+1} \right\} \\
&\quad + \sum_{n=1}^{N-1} \Delta t (p(t^{n+1}) - r_\eta p(t^{n+1}), \operatorname{div} w_\eta^n).
\end{align*}
\]

Owing to the inf-sup condition (1.10), there exists a function \(w_\eta \in V_\eta^2\) such that

\[
\| \operatorname{div} w_\eta, p_\eta^{n+1} - r_\eta p(t^{n+1}) \|_{L^2(\Omega)}^2 \leq \frac{1}{\beta^*} \| p_\eta^{n+1} - r_\eta p(t^{n+1}) \|_{L^2(\Omega)} .
\]

Let \((P_{RH})_i, i = 1, ..., 6\), denote the terms of the right-hand side of (5.2).

We deduce by standard arguments:

\[
\begin{align*}
|(P_{RH})_1| &\leq S_2 \left( \sum_{n=1}^{N-1} \Delta t \| \delta^1 e_\eta^n \|_{L^2(\Omega)}^2 \right)^{1/2} \left( \sum_{n=1}^{N-1} \Delta t |w_\eta^{n+1}|_{H^1(\Omega)}^2 \right)^{1/2}, \\
|(P_{RH})_2| &\leq \nu \left( \sum_{n=1}^{N-1} \Delta t |P_\eta u(t^{n+1}) - u(t^{n+1})|_{H^1(\Omega)}^2 \right)^{1/2} \left( \sum_{n=1}^{N-1} \Delta t |w_\eta^{n+1}|_{H^1(\Omega)}^2 \right)^{1/2}, \\
&\leq C_1 (\eta^2 + (\Delta t)^2) \left( \sum_{n=1}^{N-1} \Delta t |w_\eta^{n+1}|_{H^1(\Omega)}^2 \right)^{1/2}, \\
|(P_{RH})_3| &\leq C_2 (\Delta t)^2 \| u^{(3)} \|_{L^2(\Omega \times [0,T])^2} \left( \sum_{n=1}^{N-1} \Delta t |w_\eta^{n+1}|_{H^1(\Omega)}^2 \right)^{1/2}.
\end{align*}
\]
The fourth and fifth terms \((P_{RH})_4, (P_{RH})_5\) are bounded as follows:

\[
|(P_{RH})_4| \leq S_1^2(t) \left( \sum_{n=1}^{N-1} \Delta t |e_{\eta}^{n+1}|^2_{L^2(\Omega)} \right)^{1/2} \left( \sum_{n=1}^{N-1} \Delta t |w_{\eta}^{n+1}|^2_{H^1(\Omega)} \right)^{1/2} \\
\leq C_3 \eta^2 + (\Delta t)^2 \left( \sum_{n=1}^{N-1} \Delta t |w_{\eta}^{n+1}|^2_{H^1(\Omega)} \right)^{1/2}.
\]

\[
|(P_{RH})_5| = \frac{1}{2} \left( \sum_{n=1}^{N-1} \Delta t \left| (e_{\eta}^{n+1} \cdot \nabla u_{\eta}^{n+1}, w_{\eta}^{n+1}) - (\nabla u_{\eta}^{n+1}, w_{\eta}^{n+1}) \right| \right)^{1/2} \\
\leq S_2^2(\sup |u_{\eta}^{n+1}|_{H^1(\Omega)} \left( \sum_{n=1}^{N-1} \Delta t |e_{\eta}^{n+1}|^2_{L^2(\Omega)} \right)^{1/2} \left( \sum_{n=1}^{N-1} \Delta t |w_{\eta}^{n+1}|^2_{H^1(\Omega)} \right)^{1/2} \\
\leq C_4 \eta^2 + (\Delta t)^2 \left( \sum_{n=1}^{N-1} \Delta t |w_{\eta}^{n+1}|^2_{H^1(\Omega)} \right)^{1/2},
\]

and the last term is bounded as follows:

\[
|(P_{RH})_6| \leq C_5 \eta^2 \| p \|_{L^2(0,T; H^2(\Omega))} \left( \sum_{n=1}^{N-1} \Delta t |w_{\eta}^{n+1}|^2_{H^1(\Omega)} \right)^{1/2}.
\]

Then (5.1) follows easily by substituting these inequalities into (5.2).

We have to estimate \( \left( \sum_{n=1}^{N-1} \Delta t \| \delta^1(u_{\eta}^n - u(t^n)) \|_{L^2(\Omega)}^2 \right)^{1/2} \). This estimate is proven assuming the triangulation satisfies a milder regularity property than uniform regularity (1.9): there exists a constant \( \tilde{\tau} \) that does not depend on \( \eta \) or \( \Delta t \) such that

\[
\rho_{\min} \geq \tilde{\tau} \eta^5, \text{ where } \rho_{\min} = \inf_{\kappa \in T_\eta} \rho_\kappa.
\]

More precisely, this assumption is used in proving that \( u_{\eta}^n \) is bounded in \( L^\infty(0,T; W^{1.5/2}(\Omega))^2 \):

**Lemma 5.2.** Under the assumptions of Theorem 4.7 and if \( T_\eta \) satisfies (5.3), there exists a constant \( C \) that depends neither on \( \eta \) nor on \( \Delta t \), such that

\[
\sup_n |u_{\eta}^n|_{W^{1.5/2}(\Omega)} \leq C.
\]

**Proof.** We refer to [2] for the sketch of this proof.

**Lemma 5.3.** Under the assumptions of Theorem 4.7, there exists a constant \( C = C(u, u', u^{(3)}) \) that does not depend on \( \eta \) and \( \Delta t \), such that

\[
\left( \sum_{n=1}^{N-1} \Delta t \| \delta^1(u_{\eta}^n - u(t^n)) \|_{L^2(\Omega)}^2 \right)^{1/2} + \sqrt{\kappa} \sup_{1 \leq n \leq N} |u_{\eta}^n - u(t^n)|_{H^1(\Omega)} \\
+ \sqrt{\kappa} \sup_{1 \leq n \leq N} |2(u_{\eta}^n - u(t^n)) - (u_{\eta}^{n-1} - u(t^{n-1}))|_{H^1(\Omega)} + \sqrt{\kappa} \left( \sum_{n=1}^{N-1} |\delta^2(u_{\eta}^n - u(t^n))|_{H^1(\Omega)}^2 \right)^{1/2} \\
\leq C(\eta^2 + (\Delta t)^3/2 + \frac{\eta^3}{\sqrt{\Delta t}}).
\]
Proof. The proof is similar to that of Lemma 5.1. By taking 
\( e^i_\eta = u^i_\eta - S_\eta u(t^i) \), \( \varphi^i_\eta = u(t^i) - S_\eta u(t^i) \) and the test function \( w = w^{n+1}_\eta = \delta^1 e^{n}_\eta \) :

\[
\sum_{n=1}^{m-1} \Delta t \left\| \delta^1 e^{n}_\eta \right\|_{L^2(\Omega)}^2 + \frac{\nu}{2} \left( |e^{m-1}_n|_{H^1(\Omega)}^2 - |e^0_n|_{H^1(\Omega)}^2 + |2e^m_n - e^{m-1}_n - 2e^0_n|_{H^1(\Omega)}^2 + \sum_{n=1}^{m-1} |\delta e^{n}_\eta|_{H^1(\Omega)}^2 \right) \\
\leq \nu \left[ \sum_{n=1}^{m-1} \Delta t (\nabla \varphi^{n+1}_\eta, \nabla \delta^1 e^{n}_\eta) + \sum_{n=1}^{m-1} \Delta t (\delta^1 \varphi^{n}_\eta, \delta^1 e^{n}_\eta) + \sum_{n=1}^{m-1} R_3 \right] \\
+ \sum_{n=1}^{m-1} \Delta t \left\{ (u(t^{n+1}) \cdot \nabla u(t^{n+1}) - u^{n+1}_\eta \cdot \nabla u^{n+1}_\eta, \delta^1 e^{n}_\eta) - \frac{1}{2} \left( \text{div} (u^{n+1}_\eta u^{n+1}_\eta, \delta^1 e^{n}_\eta) \right) \right\},
\]

(5.6)

with

\[
u \sum_{n=1}^{m-1} \Delta t (\nabla \varphi^{n+1}_\eta, \nabla \delta^1 e^{n}_\eta) + \sum_{n=1}^{m-1} \Delta t \left( \delta^1 \varphi^{n}_\eta, \delta^1 e^{n}_\eta \right) + \sum_{n=1}^{m-1} R_3
\]

\[
+ \sum_{n=1}^{m-1} \Delta t \left\{ (u(t^{n+1}) \cdot \nabla u(t^{n+1}) - u^{n+1}_\eta \cdot \nabla u^{n+1}_\eta, \delta^1 e^{n}_\eta) - \frac{1}{2} \left( \text{div} (u^{n+1}_\eta u^{n+1}_\eta, \delta^1 e^{n}_\eta) \right) \right\},
\]

(5.6)

Due to the definition of the operator \( S_\eta \), we only have to estimate the three last terms \( (V_{RH})_i, i = 1, ..., 3 \), in the right-hand side of (5.6).

The first one is bounded as precedently as follows :

\[
| (V_{RH})_1 | = \left| \sum_{n=1}^{m} \Delta t (\delta^1 \varphi^{n}_\eta, \delta^1 e^{n}_\eta) \right| \leq C \left\{ \eta^4 \left( \left\| u^t \right\|_{L^\infty(0,T;H^2(\Omega))^2} + \left\| p^t \right\|_{L^\infty(0,T;H^2(\Omega))} \right)^2 + \Delta t \eta^2 \left( \left\| u^{t} \right\|_{L^2(0,T;H^2(\Omega))} + \left\| p^{t} \right\|_{L^2(0,T;H^2(\Omega))} \right) \right\} + \varepsilon_2 \sum_{n=1}^{m-1} \Delta t \left\| \delta^1 e^{n}_\eta \right\|_{L^2(\Omega)}^2.
\]

The second term is bounded as follows:

\[
| (V_{RH})_2 | = \left| \sum_{n=1}^{m-1} R_3 \right| \leq C \left( \Delta t \right)^2 \frac{\eta^4}{2} \left\| u^{t} \right\|_{L^2(0,T;H^2(\Omega))^2} + \varepsilon_3 \sum_{n=1}^{m-1} \Delta t \left\| \delta^1 e^{n}_\eta \right\|_{L^2(\Omega)}^2.
\]

For the last term, it is split into two parts that we treat successively. The first part is treated as follows:

\[
\sum_{n=1}^{m-1} \Delta t \left( (u(t^{n+1}) \cdot \nabla (u(t^{n+1}) - u^{n+1}_\eta), \delta^1 e^{n}_\eta) \right) \leq C \frac{\left\| u \right\|_{L^\infty(0,T;H^2(\Omega))^2}}{2} \left( \eta^4 + \left( \Delta t \right)^4 \right) + \varepsilon_3 \sum_{n=1}^{m-1} \Delta t \left\| \delta^1 e^{n}_\eta \right\|_{L^2(\Omega)}^2,
\]

and for the second part, we notice that :

\[
\left\| (u(t^{n+1}) - u^{n+1}_\eta) \cdot \nabla u^{n+1}_\eta \right\|_{L^2(\Omega)} \leq \left\| u^{n+1}_\eta \right\|_{W^{1,5/2}(\Omega)} \left\| u(t^{n+1}) - u^{n+1}_\eta \right\|_{L^\infty(\Omega)} \leq S_{10} \left\| u^{n+1}_\eta \right\|_{W^{1,5/2}(\Omega)} \left\| u(t^{n+1}) - u^{n+1}_\eta \right\|_{H^1(\Omega)},
\]

then it is bounded as follows :

\[
\sum_{n=1}^{m-1} \Delta t \left( \left( (u(t^{n+1}) - u^{n+1}_\eta) \cdot \nabla u^{n+1}_\eta, \delta^1 e^{n}_\eta \right) + \frac{1}{2} \left( \left( \text{div} (u(t^{n+1}) - u^{n+1}_\eta) u^{n+1}_\eta, \delta^1 e^{n}_\eta \right) \right) \right) \leq \left( C \frac{2}{2} + S_{10} \right) \left\| u^{n+1}_\eta \right\|_{W^{1,5/2}(\Omega)} \sum_{n=1}^{m-1} \Delta t \left| u(t^{n+1}) - u^{n+1}_\eta \right|_{H^1(\Omega)} \left\| \delta^1 e^{n}_\eta \right\|_{L^2(\Omega)} \leq C \varepsilon_4 \left( \eta^4 + \left( \Delta t \right)^4 \right) + \varepsilon_4 \sum_{n=1}^{m-1} \Delta t \left\| \delta^1 e^{n}_\eta \right\|_{L^2(\Omega)}^2.
\]
Then by setting $C_1 = \| u \|_{L^\infty(\Omega \times [0,T])}$, the last term of the right-hand side of (5.6) is bounded by:

$$
\left( \frac{C_1 C'}{2 \varepsilon_i} + C'' \varepsilon_i \right) (\eta^4 + (\Delta t)^4) + \left( \frac{C_1 \varepsilon_3}{2} + C'' \varepsilon_1 \right) \sum_{n=1}^{m-1} \Delta t \| \delta^1 c_n \|_{L^2(\Omega)}^2.
$$

Finally the initial datas are bounded due to Proposition 3.3. Then, choosing suitably the parameters $\varepsilon_i$, the equation (5.6) becomes

$$
\left( \sum_{n=1}^{m-1} \Delta t \| \delta^1 (u_n^i - S_\eta u(t^n)) \|_{L^2(\Omega)}^2 \right)^{1/2} + \sqrt{\nu} \sup_{1 \leq n \leq N} |u_n^i - S_\eta u(t^n)|_{H^1(\Omega)}
$$

$$
+ \sqrt{\nu} \sup_{1 \leq n \leq N} |2(u_n^i - S_\eta u(t^n)) - (u_n^{i-1} - S_\eta u(t^{n-1}))|_{H^1(\Omega)} + \sqrt{\nu} \left( \sum_{n=1}^{N-1} |\delta^1 (u_n^i - S_\eta u(t^n))|_{H^1(\Omega)}^2 \right)^{1/2}
$$

$$
\leq C(\eta^2 + (\Delta t)^{3/2} + \frac{\eta^3}{\sqrt{\Delta t}}).
$$

Finally (5.5) follows readily from this result and by applying a triangular inequality and $S_\eta$'s properties.

From these three lemmas, we easily derive an estimate of the pressure.

**Theorem 5.4.** Under the assumptions of Lemma 5.1, there exists a constant $C$ that does not depend on $\eta$ nor on $\Delta t$, such that

$$
\left( \sum_{n=1}^{N} \Delta t \| p(t^n) - p_\eta^i \|_{L^2(\Omega)}^2 \right)^{1/2} \leq C(\eta^2 + (\Delta t)^{3/2} + \frac{\eta^3}{\sqrt{\Delta t}}).
$$

(5.7)

6. **Error estimate for the solution of Step Two**

We assume at this stage that we know the solution $u_{H}^{i+1}$ of the first step. Then at each time step, the second step (1.19)–(1.20) is a square system of linear equations in finite dimension, and if $\Delta t$ is small enough, it has a unique solution. First, we will establish the error estimate for the solution computed by one step of Euler’s scheme ($u_{H}^i - u(\Delta t), p_{H}^i - p(\Delta t)$):

**Proposition 6.1.** The error of the solution computed by one iteration of Euler’s scheme satisfies the following estimations, for $\Delta t \leq k_0 > 0$ sufficiently small,

$$
\frac{1}{2} \| u_{H}^i - u(\Delta t) \|_{L^2(\Omega)}^2 + \frac{\nu \Delta t}{2} \| u_{H}^i - u(\Delta t) \|_{H^1(\Omega)}^2 \leq C(\nu^2 + (\Delta t)^4),
$$

(6.1)

and

$$
(\Delta t)^{1/2} \| p(\Delta t) - p_{H}^i \|_{L^2(\Omega)} \leq C(\nu^2 + (\Delta t)^{3/2}).
$$

(6.2)

**Proof.** The error’s equation is similar to (3.2).

$$
\forall v_h \in V_h, (u_{H}^i - u(\Delta t), v_h) + \nu \Delta t(\nabla (u_{H}^i - u(\Delta t)), \nabla v_h) = \frac{(\Delta t)^2}{2} (u''(\theta \Delta t), v_h)
$$

$$
- \Delta t \nu (p(\Delta t) - r_k p(\Delta t), \text{div } v_h) + \Delta t(\text{div } u(\Delta t), \nabla u(\Delta t) - u_{H}^i \cdot \nabla u_{H}^i, v_h).
$$

(6.3)

By setting $v_h = u_{H}^i = P_h u(\Delta t) - u_{H}^i$ and $\varphi_h = P_h u(\Delta t) - u(\Delta t)$, the non-linear term can be written as follows:

$$
(\Delta t) \cdot \nabla u(\Delta t) - u_{H}^i \cdot \nabla u_{H}^i, v_h) = ((u(\Delta t) - u_{H}^i) \cdot \nabla u(\Delta t), v_h) + (u_{H}^i \cdot \nabla (u(\Delta t) - P_h u(\Delta t)), v_h)
$$

$$
+ ((u(\Delta t) - u_{H}^i) \cdot \nabla u_{H}^i, v_h) + (u(\Delta t) \cdot \nabla (P_h u(\Delta t) - u_{H}^i), v_h)
$$

$$
= ((u(\Delta t) - u_{H}^i) \cdot \nabla u(\Delta t), v_h) - (u_{H}^i \cdot \nabla \varphi_h, v_h) - ((u(\Delta t) - u_{H}^i) \cdot \nabla v_h, v_h).
$$
Then, we have three contributions of the non-linear term. For the first part, we write:

\[
\Delta t \left( (u(\Delta t) - u_h^t) \cdot \nabla u(\Delta t), v_h^t \right) \leq S_1 |v_h^t|_{H^1(\Omega)} \sup_t |u(\Delta t)|_{W^{1,4}(\Omega)} \Delta t \|u(\Delta t) - u_H^{n+1}\|_{L^2(\Omega)} \leq \frac{1}{2} \left( \varepsilon_1 \Delta t |v_h^t|_{H^1(\Omega)}^2 + \frac{1}{\varepsilon_1} C^2 \Delta t (H^6 + (\Delta t)^4 + (\Delta t)H^4) \right).
\]

For the second part, we know that $\|u_H^t\|_{L^4(\Omega)}$ is bounded and we write:

\[
\Delta t \left( (u_H^t \cdot \nabla \varphi_h^t, v_h^t) \right) \leq S_2 \Delta t |v_h^t|_{H^1(\Omega)} \|u_H^t\|_{L^4(\Omega)} \|u(\Delta t) - P_H u(\Delta t)\|_{H^1(\Omega)} \leq \frac{1}{2} \left( \varepsilon_2 \Delta t |v_h^t|_{H^1(\Omega)}^2 + \frac{C}{\varepsilon_2} (\Delta t)h^4 \right).
\]

Finally, the last term can be written as:

\[
\Delta t \left( (u(\Delta t) - u_H^t) \cdot \nabla v_h^t, v_h^t \right) \leq \Delta t \tilde{C} H^{1-\varepsilon} |v_h^t|_{H^1(\Omega)}^2 \|u_H^t - u(\Delta t)\|_{H^1(\Omega)},
\]

with

\[
\|u_H^t - u(\Delta t)\|_{H^1(\Omega)} \leq C((\Delta t)^{3/2} + H^2 + \frac{H^3}{\sqrt{\Delta t}}).
\]

In that case, for $H$ (and $\Delta t$) sufficiently smooth, this term is absorbed by the left-hand side of the equation. And for the linear terms, we introduce $P_h u(\Delta t)$ in (6.3) and we obtain:

\[
\|v_h^t\|_{L^2(\Omega)}^2 + \nu \Delta t |v_h^t|_{H^1(\Omega)}^2 \leq \left( |\varphi_h^t, v_h^t| + \nu \Delta t \left( \|
abla \varphi_h^t, \nabla v_h^t\| \right) + \frac{(\Delta t)^2}{2} \sup |u''|_{L^2(\Omega)} \|v_h^t\|_{L^2(\Omega)} + \Delta t \left\| p(\Delta t) - r_h p(\Delta t) \right\|_{L^2(\Omega)} \|v_h^t\|_{H^1(\Omega)} \] \quad \text{non-linear term.}
\]

For the pressure, we obtain:

\[
\Delta t (r_h p(\Delta t) - p(\Delta t), \text{div} v_h) + \Delta t (p_h^t - r_h p(\Delta t), \text{div} v_h)
= (u_h^t - u(\Delta t), v_h) + \nu \Delta t (\nabla (u_h^t - u(\Delta t)), \nabla v_h) - \frac{(\Delta t)^2}{2} (u''(\theta \Delta t), v_h) - \Delta t (u(\Delta t) \cdot \nabla u(\Delta t) - u_h^t \cdot \nabla v_h, v_h).
\]

We choose $v_h \in V_h^{1,4}$ such that

\[
(p_h^t - r_h p(\Delta t), \text{div} v_h) = \|p_h^t - r_h p(\Delta t)\|_{L^2(\Omega)}^2 \quad \text{and} \quad \|v_h\|_{H^1(\Omega)} \leq \frac{1}{\beta^*} \|p_h^t - r_h p(\Delta t)\|_{L^2(\Omega)},
\]

with $\beta^* > 0$ that does not depend on $h$. Thus

\[
(\Delta t)^{1/2} \|p_h^t - r_h p(\Delta t)\|_{L^2(\Omega)} \leq \frac{(\Delta t)^{1/2}}{\beta^*} \left( \|r_h p(\Delta t) - p(\Delta t)\|_{L^2(\Omega)} + \frac{S_2}{\Delta t} \|u_h^t - u(\Delta t)\|_{L^2(\Omega)} + \nu |P_h u(\Delta t) - u(\Delta t)|_{H^1(\Omega)} + \frac{S_2}{2} (\|u''(\theta \Delta t)\|_{L^2(\Omega)} + S_4^2 (|u(\Delta t)|_{H^2(\Omega)} + |u_H^t|_{H^1(\Omega)}) \|u_h^t - u(\Delta t)\|_{H^1(\Omega)}) \right) \leq C(h^2 + H^3 + (\Delta t)^{3/2}).
\]

The fine velocity satisfies the following error estimate:

**Theorem 6.2.** Under the hypotheses of Theorem 4.7, the solution of Step 2, $(u_h^{n+1}, p_h^{n+1})$, satisfies the following error estimate:

\[
\sup_{1 \leq n \leq N} \|u_h^n - u(t^n)\|_{L^2(\Omega)} + \sup_{1 \leq n \leq N} \|p(u_h^n - u(t^n)) - (u_h^{n-1} - u(t^{n-1}))\|_{L^2(\Omega)} + \sum_{n=1}^N \|\Delta t (u_h^n - u(t^n))\|_{L^2(\Omega)}^{1/2} + \sqrt{p} \sum_{n=1}^N \Delta t |u_h^n - u(t^n)|_{H^1(\Omega)}^{1/2} \leq C(h^2 + H^2 + (\Delta t)^2 + H(\Delta t)^2),
\]

with a constant $C$ that does not depend on $h, H$ and $\Delta t$. 
Proof. By substructing the equations (1.19) and (1.17), by setting \(v^n_h = P_h u(t^n) - u_{h,i}^n\), \(\varphi^n_h = P_h u(t^n) - u(t^n)\), by taking the test function \(v^n_h = v^n_{h,1}\) and by summing the result from \(n = 1\) to \(n = m - 1\), we obtain

\[
\nu \sum_{n=1}^{m-1} \Delta t |v^n_{h,1}|^2_{H^1(\Omega)} + \frac{1}{4} \left( |v^n_m|^2_{L^2(\Omega)} - |v^n_h|^2_{L^2(\Omega)} + |2v^n_m - v^n_h|^2_{L^2(\Omega)} - |2v^n_m - v^n_h|^2_{L^2(\Omega)} + \sum_{n=1}^{m-1} \| \Delta_t^2 v^n_h \|^2_{L^2(\Omega)} \right) \leq \left| \sum_{n=1}^{m-1} R_t \right| + \nu \sum_{n=1}^{m-1} \Delta t (\varphi^n_{h,1}, \varphi^n_{h,1}) + \left| \sum_{n=1}^{m-1} \Delta t (p(t^n+1) - rh(t^n+1), \text{div} v^n_{h,1}) \right| + \left| \sum_{n=1}^{m-1} \Delta t (u^n_{h,1}, \text{div} v^n_{h,1}, u^n_{h,1}) \right|.
\]

(6.7)

Let us estimate the terms \((TG_{RH})i, i = 1, ..., 4\) in the right-hand side of (6.7). The first term is bounded as follows:

\[
|(TG_{RH})1| \leq \frac{C(\Delta t)^4}{2\varepsilon_1} \| u^{(3)} \|^2_{L^2(\Omega \times [0,T])^2} + \frac{\varepsilon_2}{2} \sum_{n=1}^{m-1} \Delta t |v^n_{h,1}|^2_{L^2(\Omega)}.
\]

The second term and third terms are bounded respectively as follows:

\[
|(TG_{RH})2| \leq \frac{C M^4}{2\varepsilon_2} \| u \|^2_{L^2(0,T;H^2(\Omega)^2)} + \frac{\nu\varepsilon_1}{2} \sum_{n=1}^{m-1} \Delta t |v^n_{h,1}|^2_{H^1(\Omega)}
\]

and

\[
|(TG_{RH})3| \leq \frac{C H^4}{2\varepsilon_3} \| p \|^2_{L^2(0,T;H^2(\Omega))} + \frac{\varepsilon_3}{2} \sum_{n=1}^{m-1} \Delta t |v^n_{h,1}|^2_{H^1(\Omega)}
\]

and the fourth term is as follows:

\[
\left| \sum_{n=1}^{m-1} \Delta t (\varphi^n_{h,1}, v^n_{h,1}) \right| \leq \frac{C(\Delta t)^4}{2\varepsilon_4} \| u^{(3)} \|^2_{L^2(\Omega \times [0,T])^2} + \frac{C H^4}{2\varepsilon_4} \| u' \|^2_{L^2(0,T;H^2(\Omega)^2)} + \frac{\varepsilon_4}{2} \sum_{n=1}^{m-1} \Delta t |v^n_{h,1}|^2_{L^2(\Omega)}.
\]

The non-linear term in the right-hand side can be written as follows:

\[
u u^n_{h,1} \cdot \nabla u^n_{h,1} - u(t^n+1) \cdot \nabla u(t^n+1) = (u^n_{h,1} - u(t^n+1)) \cdot \nabla u(t^n+1) + u^n_{h,1} \cdot \nabla (P_h u(t^n+1) - u(t^n+1)) - (u(t^n+1) - u(t^n+1)) \cdot \nabla (u^n_{h,1} + P_h u(t^n+1) - u(t^n+1)).
\]

We study the four parts \((NL)_i, i = 1, ..., 4\), of the non-linear term separately. Setting \(C_{(NL)1} = \sup \| u \|^2_{W^{1,4}(\Omega)}\), the first part is treated as follows:

\[
\left| \sum_{n=0}^{m-1} \Delta t ((NL)_1, v^n_{h,1}) \right| \leq \frac{C_{(NL)2}}{2\varepsilon_5} \| u \|^2_{L^2(0,T;H^2(\Omega)^2)} + \frac{\varepsilon_5}{2} \sum_{n=1}^{m-1} \Delta t |v^n_{h,1}|^2_{H^1(\Omega)}.
\]

Choosing \(C_{(NL)2} = \sup \| u^{n+1}_{h,1} \|_{L^4(\Omega)}\), the second part is treated as follows:

\[
\left| \sum_{n=0}^{m-1} \Delta t ((NL)_2, v^n_{h,1}) \right| \leq \frac{C C_{(NL)2}}{2\varepsilon_6} \| u |_{L^2(0,T;H^2(\Omega)^2)}^2 + \frac{\varepsilon_6}{2} \sum_{n=1}^{m-1} \Delta t |v^n_{h,1}|^2_{H^1(\Omega)}.
\]

For the third part, we use the following estimation (cf. [7]): there exists a constant \(\tilde{C}\), that does not depend on \(\eta\) such that, for all \(u_n \in V_h\),

\[
\forall u_n \in X_h, |u_n \cdot \nabla w_n, w_n| \leq \tilde{C} \eta^{-\varepsilon} \| \text{div} u_n \|_{L^2(\Omega)} |w_n|^2_{H^1(\Omega)}.
\]

we have

\[
\left| \sum_{n=0}^{m-1} \Delta t ((NL)_3, v^n_{h,1}) \right| \leq \tilde{C} H^{1-\varepsilon} (H^2 + (\Delta t)^{3/2} + \frac{H^3}{\sqrt{\Delta t}}) \sum_{n=1}^{m-1} \Delta t |v^n_{h,1}|^2_{H^1(\Omega)}.
\]

And the last part is bounded as follows:

\[
\left| \sum_{n=0}^{m-1} \Delta t ((NL)_4, v^n_{h,1}) \right| = 0.
\]
Then, collecting these inequalities, choosing suitably the parameters \( \varepsilon_i \) and \( \delta \) and applying Gronwall’s Lemma, we get

\[
\sup_{1 \leq n \leq N} \| u_h^n - P_h u(t^n) \|_{L^2(\Omega)} + \sup_{1 \leq n \leq N} \| 2(u_h^n - P_h u(t^n)) - (u_h^{n-1} - P_h u(t^{n-1})) \|_{L^2(\Omega)} \\
+ (\sum_{n=1}^{N-1} \| \delta^2(u_h^n - P_h u(t^n)) \|_{L^2(\Omega)})^{1/2} + \sqrt{\nu} (\sum_{n=1}^{N} \Delta t |u_h^n - P_h u(t^n)|^2_{H^1(\Omega)})^{1/2} \\
\leq C(H^3 + h^2 + (\Delta t)^2).
\]

Then, (6.6) follows readily from the above result and the \( P_h \)’s properties. \( \square \)

Finally, we consider the error of the pressure. As in Section 5, the pressure satisfies the following bound.

**Lemma 6.3.** Let \((u(t^{n+1}), p(t^{n+1}))\) and \((u_h^{n+1}, p_h^{n+1})\) be the respective solution of (1.1)–(1.4) and (1.19)–(1.20). We have

\[
(\sum_{n=1}^{N-1} \Delta t \| p_h^{n+1} - p(t^{n+1}) \|_{L^2(\Omega)})^{1/2} \leq \frac{1}{\beta^*} \left\{ C_1 h^2 \| p \|_{L^2(0,T;H^2(\Omega))} + C_2 (\Delta t)^2 \| u^{(3)} \|_{L^2(\Omega)} \right. \\
+ C_3 (H^3 + (\Delta t)^2) + C_4 h^2 + S_2 \left( \sum_{n=1}^{N-1} \Delta t \| \delta u_h^n - u(t^n) \|_{L^2(\Omega)} \right)^{1/2},
\]

where \( \beta^* \) is the constant of the inf-sup condition (1.10) and the coefficients \( C_i, i = 1, \ldots, 4 \), do not depend on \( H, h \) and \( \Delta t \).

**Proof.** The steps of this proof are similar to those of the proof of Lemma 5.1 and the only difference between these proofs concerns the non-linear term. Here we write

\[
u(t^{n+1}) \cdot \nabla u(t^{n+1}) - u_h^{n+1} \cdot \nabla p_h^{n+1} = (u(t^{n+1}) - u_h^{n+1}) \cdot \nabla u(t^{n+1}) + (u_h^{n+1} - u(t^{n+1})) \cdot \nabla (u(t^{n+1}) - u_h^{n+1}) \\
+ u(t^{n+1}) \cdot \nabla (u(t^{n+1}) - u_h^{n+1}).
\]

Then, let us estimate the terms that compose the non-linear term.

\[
\left| \sum_{n=1}^{N-1} \Delta t (u(t^{n+1}) \cdot \nabla u(t^{n+1}) - u_h^{n+1} \cdot \nabla u_h^{n+1} + u_h^{n+1}) \right| \\
\leq S_4 \left( \sum_{n=1}^{N-1} \Delta t |u_h^{n+1}|_{H^1(\Omega)}^2 \right)^{1/2} \left( \sup_n |u(t^n)|_{H^{1.5}(\Omega)} \right) \left( \sum_{n=1}^{N-1} \Delta t \| u(t^{n+1}) - u_h^{n+1} \|_{L^2(\Omega)} \right)^{1/2} \\
+ S_4 (\sup_n |u(t^n)|_{H^1(\Omega)} + \sup_n |u(t^n)|_{H^1(\Omega)}) \left( \sum_{n=1}^{N-1} \Delta t |u(t^{n+1}) - u_h^{n+1}|_{H^1(\Omega)}^2 \right)^{1/2} \\
\leq (C(H^3 + (\Delta t)^2) \left( \sum_{n=1}^{N-1} \Delta t |w_h^{n+1}|_{H^1(\Omega)}^2 \right)^{1/2}.
\]

Then, (6.9) follows readily from these bounds and from the inf-sup condition (1.10). \( \square \)

Therefore, here again, we must derive an estimate for

\[
\left( \sum_{n=1}^{N-1} \Delta t \| \delta u_h^n - u(t^n) \|_{L^2(\Omega)}^2 \right)^{1/2}.
\]
Lemma 6.4. Under the assumptions of Theorem 4.7 and Corollary 3.4, there exists a constant $C$ that does not depend on $H, h$ and $\Delta t$ such that:

\[
\left( \sum_{n=1}^{N-1} \Delta t \| \delta^1(u^n_h - u(t^n)) \|_{L^2(\Omega)}^2 \right)^{1/2} + \sqrt{\nu} \sup_{1 \leq n \leq N} \left| u^n_h - u(t^n) \right|_{H^1(\Omega)} + \sqrt{\nu} \sup_{1 \leq n \leq N} \left| 2(u^n_h - u(t^n)) - (u^{n-1}_h - u(t^{n-1})) \right|_{H^1(\Omega)} + \sqrt{\nu} \left( \sum_{n=1}^{N-1} \| \delta^2(u^n_h - u(t^n)) \|_{H^1(\Omega)}^2 \right)^{1/2} \leq C(h^2 + H^3 + (\Delta t)^2). \tag{6.10}
\]

Proof. We substruct the equations (1.17) and (1.19), we set $e_h = u^n_h - S_h u(t^n)$ and $\varphi_h = u(t^n) - S_h u(t^n)$ and we take the function test $w_h = \delta^1 e^n_h$. Due to the definition of the Stokes operator $S_h$, we have

\[
\sum_{n=1}^{m-1} \Delta t \| \delta^1 e^n_h \|_{L^2(\Omega)}^2 + \frac{\nu}{2} \sum_{n=1}^{m-1} \Delta t \left( \nabla e^n_h \cdot \nabla \delta^1 e^n_h \right) = \sum_{n=1}^{m-1} \Delta t \left( \delta^1 \varphi^n_h \cdot \delta^1 e^n_h \right) + \sum_{n=1}^{m-1} R_l + \sum_{n=1}^{m-1} \Delta t \left( u(t^{n+1}) \cdot \nabla u(t^{n+1}) - u_H^{n+1} \cdot \nabla u_H^{n+1}, \delta^1 e^n_h \right). 
\]

The first term of the right-hand side is bounded as follows:

\[
\left| \sum_{n=1}^{m-1} \Delta t \left( \delta^1 \varphi^n_h \cdot \delta^1 e^n_h \right) \right| \leq \frac{C}{2\varepsilon_1} \left( h^4 \left\| u' \right\|_{L^\infty(0,T;H^2(\Omega)^2)} + \| p' \|_{L^\infty(0,T;H^1(\Omega)^2)} + \| \Delta t \|^{1/2} \left\| \delta^1 e^n_h \right\|_{L^2(\Omega)}^2 \right).
\]

The second term is bounded as follows:

\[
\left| \sum_{n=1}^{m-1} R_l \right| \leq \frac{C(\Delta t)^4}{2\varepsilon_2} \left( \| u^{(3)} \|_{L^2(\Omega \times [0,T])^2} + \| p'' \|_{L^2(\Omega \times [0,T])} \right) + \frac{\varepsilon_2}{2} \sum_{n=1}^{m-1} \Delta t \left\| \delta^1 e^n_h \right\|_{L^2(\Omega)}^2.
\]

Setting $C_{\infty} = \sup_n \| u(t^{n+1}) \|_{L^\infty(\Omega)}$, the third term is bounded as follows:

\[
\left| \sum_{n=1}^{m-1} \Delta t \left( u(t^{n+1}) - u_H^{n+1} \right) \cdot \nabla u(t^{n+1}), \delta^1 e^n_h \right| \leq \frac{C_{\infty} \varepsilon_3}{2\varepsilon_2} \sum_{n=1}^{m-1} \Delta t \left\| \delta^1 e^n_h \right\|_{L^2(\Omega)}^2.
\]

Using Theorem 6.2, the fourth and fifth terms are respectively bounded as follows:

\[
\left| \sum_{n=1}^{m-1} \Delta t \left( u_H^{n+1} - u(t^{n+1}) \right) \cdot \nabla (u(t^{n+1}) - u_H^{n+1}), \delta^1 e^n_h \right| \leq \frac{S_2^2}{2\varepsilon_4} \left( \sup_n \| u(t^{n+1}) - u_H^{n+1} \|_{L^\infty(\Omega)^2} \right)^2 \sum_{n=1}^{m-1} \Delta t \left\| u(t^{n+1}) - u_H^{n+1} \right\|_{H^1(\Omega)}^2 + \frac{S_2^2 \varepsilon_4}{2} \sum_{n=1}^{m-1} \Delta t \left\| \delta^1 e^n_h \right\|_{L^2(\Omega)}^2
\]

and

\[
\left| \sum_{n=1}^{m-1} \Delta t \left( u(t^{n+1}) \cdot \nabla (u(t^{n+1}) - u_H^{n+1}), \delta^1 e^n_h \right) \right| \leq \frac{C_{\infty} \varepsilon_5}{2\varepsilon_5} \left( C(H^6 + h^4 + (\Delta t)^4) + \frac{C_{\infty} \varepsilon_5}{2} \sum_{n=1}^{m-1} \Delta t \left\| \delta^1 e^n_h \right\|_{L^2(\Omega)}^2 \right).
\]
Thus, after a suitable choice of $\varepsilon_i$, $i = 1, \ldots, 4$ and by applying the error of the solution computed by one iteration of Euler’s scheme established in Proposition 3.3, we obtain

$$
\left( \sum_{n=1}^{N-1} \Delta t \left\| \delta^1 e_h^n \right\|^2_{L^2(\Omega)} \right)^{1/2} + \sqrt{\nu} \sup_{1 \leq n \leq N} |e_h^n|_{H^1(\Omega)} + \sqrt{\nu} \sup_{1 \leq n \leq N} |2e_h^n - e_h^{n-1}|_{H^1(\Omega)} + \sqrt{\nu} \left( \sum_{n=1}^{N-1} |\delta^2 e_h^n|^2_{L^2(\Omega)} \right)^{1/2} \leq C(h^2 + H^3 + (\Delta t)^2).
$$

These two lemmas yield immediately the following theorem.

**Theorem 6.5.** Under the assumptions of Lemma 6.4, we have:

$$
\left( \sum_{n=1}^{N-1} \Delta t \left\| p(t^{n+1}) - p_h^{n+1} \right\|^2_{L^2(\Omega)} \right)^{1/2} \leq C(h^2 + H^3 + (\Delta t)^2),
$$

with a constant $C$ that does not depend on $h$, $H$ and $\Delta t$.

**Remark 6.6.** As a consequence, $h$, $H$ and $\Delta t$ satisfy (3.16), then

$$
\left( \sum_{n=1}^{N-1} \Delta t \left\| p(t^{n+1}) - p_h^{n+1} \right\|^2_{L^2(\Omega)} \right)^{1/2} \leq Ch^2.
$$

This theoretical analysis is confirmed by numerical results cf. [1].

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**References**


