

Smart Farming, Learning and PDE

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Work in collaboration with Hélène Flourent, PhD candidate of the LMBA and working at Neovia

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AI, Machine Learning and Data Assimilation

AI - When?

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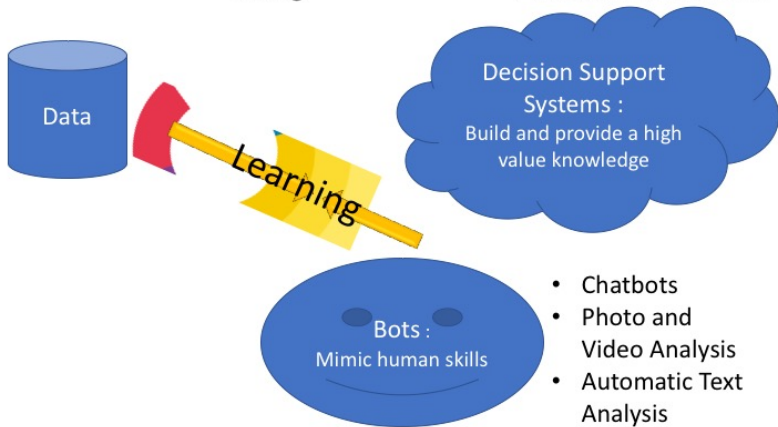
Real Animal,
Avatar &
Involved PDE

Application

Conclusion

- Forecasts
- Optimization
- Pricing

- Enterprise Driving
- Smart Farming
- Predictive Maintenance



- Chatbots
- Photo and Video Analysis
- Automatic Text Analysis

AI - Beyond Data Analysis

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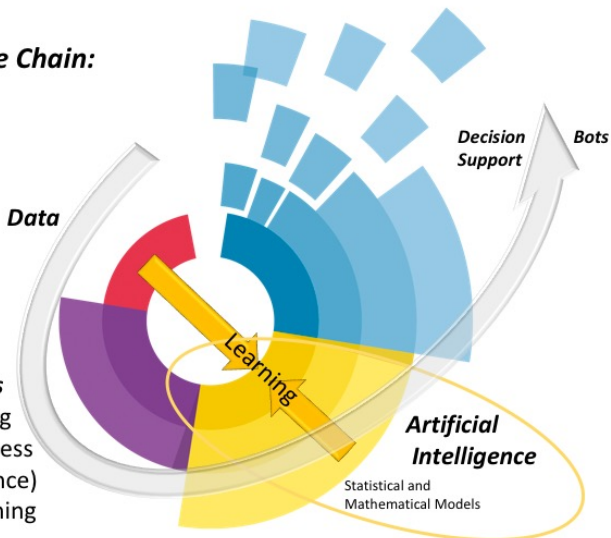
Application

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Data Value Chain:

Traditional Data Analysis

- Reporting
- BI (Business Intelligence)
- Data Mining



Learning and PDE (or ODE)

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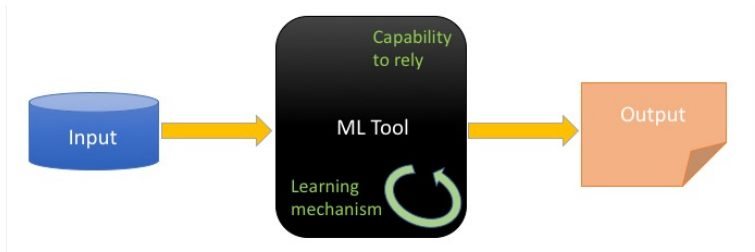
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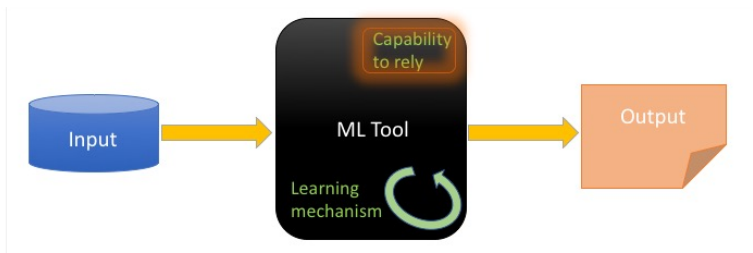
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$$\frac{\partial u}{\partial t} - c\Delta u = 0,$$

$$u_{t=0} = u_0,$$

$$u_{t=1}.$$

Learning and PDE (or ODE)

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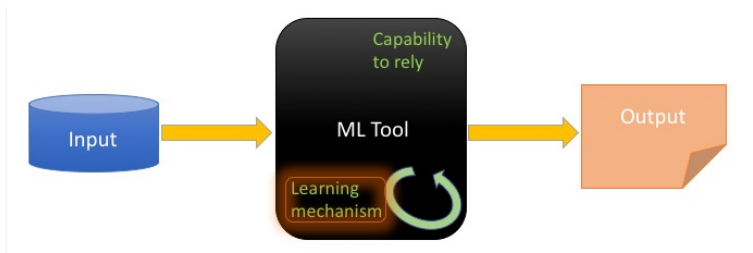
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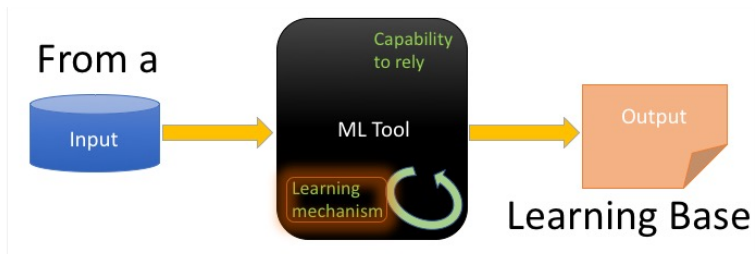
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Advantages of this "Model Data Coupling" Approach

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- Embeds scientific and/or business knowledge
- Allows AI in a Small Data context
- Allows AI in a Big Data context as well
- Allows AI in a Heterogeneous Data context
- Can accompany transition from Small to Big Data

Drawbacks of this "Model Data Coupling" Approach

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Demands working a bit more than just integrating existing API or functions

Yet, even more: Data Assimilation

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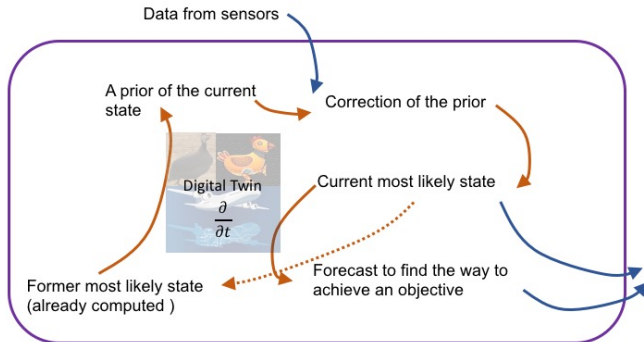
Application

Conclusion

When

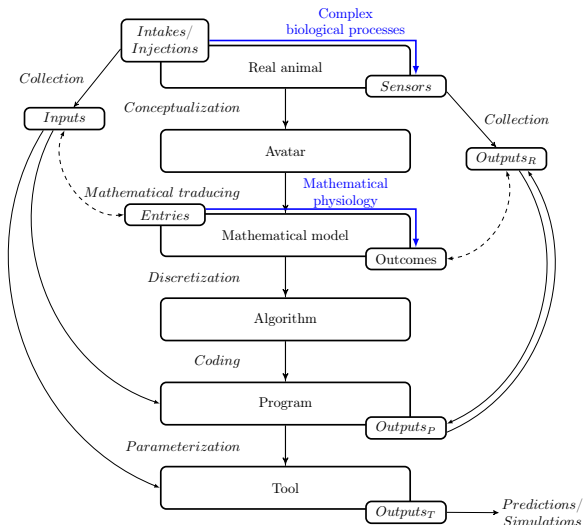
$$\frac{\partial}{\partial t}$$

Numerical Twin for Data Assimilation:



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Avatar



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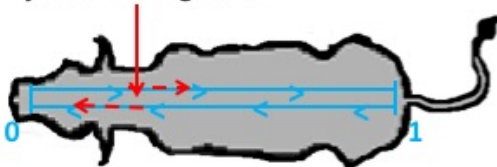
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$$t \in [0, \infty), \mathbf{x} \in (0, 1)$$

Injection or ingestion



Avatar

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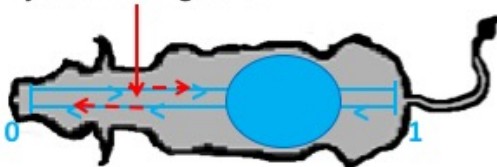
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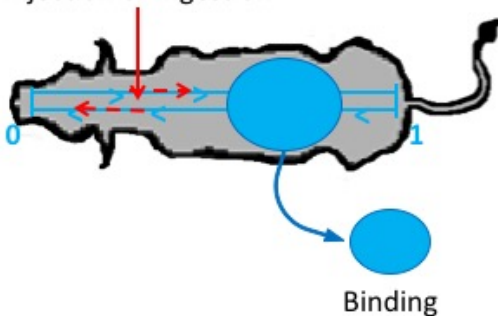
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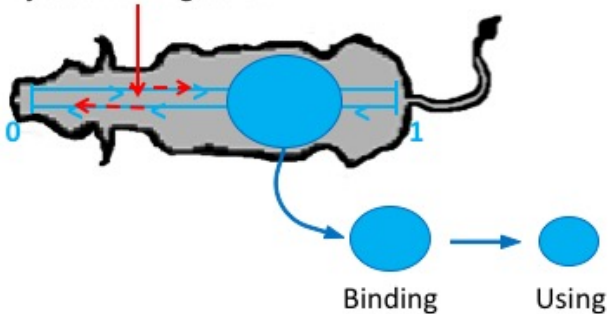
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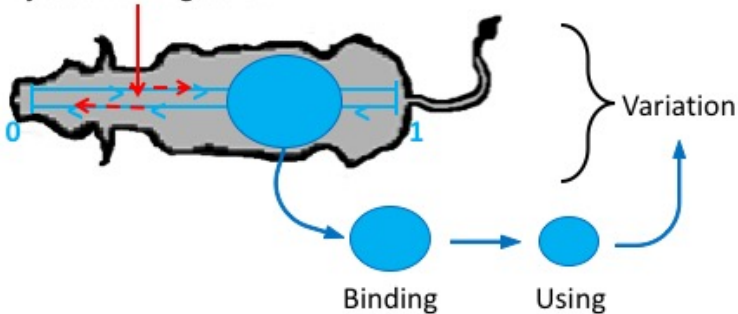
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Involved PDE - 1

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$$\begin{aligned} & \frac{\partial \{\Phi_f(d)\}}{\partial t}(t, \mathbf{x}) + \omega_d \frac{\partial \{\Phi_f(d)\}}{\partial \mathbf{x}}(t, \mathbf{x}) - \frac{\partial \left[c_d \chi \frac{\partial [\{\Phi_f(d)\} + \{\Phi_b(d)\}]}{\partial \mathbf{x}} \right]}{\partial \mathbf{x}}(t, \mathbf{x}) \\ &= \frac{1}{2} \{Q(d)\}(t, \mathbf{x}) - f_d \{F(d)\}(\mathbf{x}) \{\Phi_f(d)\}(t, \mathbf{x}) - r_d \{\Phi_f(d)\}(t, \mathbf{x}), \quad (1) \end{aligned}$$

$$\begin{aligned} & \frac{\partial \{\Phi_b(d)\}}{\partial t}(t, \mathbf{x}) - \omega_d \frac{\partial \{\Phi_b(d)\}}{\partial \mathbf{x}}(t, \mathbf{x}) - \frac{\partial \left[c_d \chi \frac{\partial [\{\Phi_f(d)\} + \{\Phi_b(d)\}]}{\partial \mathbf{x}} \right]}{\partial \mathbf{x}}(t, \mathbf{x}) \\ &= \frac{1}{2} \{Q(d)\}(t, \mathbf{x}) - f_d \{F(d)\}(\mathbf{x}) \{\Phi_b(d)\}(t, \mathbf{x}) + r_d \{\Phi_f(d)\}(t, \mathbf{x}) \quad (2) \end{aligned}$$

$$\begin{aligned} \frac{\partial \{\Psi(d)\}}{\partial t}(t, \mathbf{x}) &= f_d \{F(d)\}(\mathbf{x}) \left[\{\Phi_f(d)\} + \{\Phi_b(d)\} \right](t, \mathbf{x}) \\ &\quad - u_d \{\Psi(d)\}(t, \mathbf{x}). \quad (3) \end{aligned}$$

Involved PDE - 2

$$\frac{\partial \{\Xi(\mathbf{d})\}}{\partial t}(t, \mathbf{x}) = u_{\mathbf{d}} \{\Psi(\mathbf{d})\}(t, \mathbf{x}), \quad (4)$$

or

$$\frac{\partial \{\Xi(\mathbf{d})\}}{\partial t}(t, \mathbf{x}) = u_{\mathbf{d}} \{\Psi(\mathbf{d})\}(t, \mathbf{x}) \left(\frac{L_{\mathbf{d}} - \{s(\mathbf{d})\}(t)}{L_{\mathbf{d}}} \right), \quad (5)$$

$$\{s(\mathbf{d})\}(t) = \int_{\Omega(\mathbf{d})} \{\Xi(\mathbf{d})\}(t, \mathbf{x}) \, d\mathbf{x}. \quad (6)$$

$$(\Omega(\mathbf{d}) = (0, 1))$$

Involved PDE - 3

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Input : $\{Q(d)\}$ Output : $\{s(d)\}$

Boundary conditions :

- Diffusion is made evanescent near 0 and 1 via χ .
- $\{\Phi_f(d)\} = \{\Phi_b(d)\}$ in 0 and $\{\Phi_b(d)\} = \{\Phi_f(d)\}$ in 1.
- Not needed for $\{\Psi(d)\}$, $\{\Xi(d)\}$ and $\{s(d)\}$

Initial conditions :

- Everything at 0
- Or at the right value when the process is in progress

Application : Predict the
weight of a farm animal at the
end of a fattening period

- First Farm
 - 7 animals
 - Weight at
 - Beginning
 - After 29 days
 - After 64 days
 - After 105 days
 - Feed consumption
- Second Farm
 - 8 animals
 - Weight at
 - Beginning
 - After 42 days
 - Feed consumption

Small Data context

Then :

- Reduce the number of parameters : f_d , u_d and L_d
- Implementation of a "sampling" or "bootstrap" method

First use case - Setting

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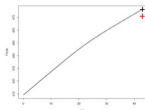
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- Adjusted parameters : f_a , u_a and L_a
- "Sampling" or "bootstrap" method: 7 adjustments on 6 animals of the First Farm
- Fitting function for the Learning : Weights after 29 days, 64 days and 105 days
- Test on the 8 animals of the Second Farm : Weight after 42 days



First use case - Results

Parameter Adjustment

	-5588	-5595	-6097	-7672	-9852	-6100	-7664	Variance relative	moyenne
f_d	5,5	5,4	6,1	5,6	5,5	5,7	5,6	0,01	5,63
L_d	800	800	782	800	772	781	780	0,18	787,86
u_d	1	0,98	1	1	0,57	0,61	0,72	0,05	0,84

Test :

id	J0	J42	Pred42	Erreur	Erreur relative
5461	414,5	515,5	502,2	-13,3	0,026
7976	427,5	503,5	505,5	2,0	0,004
8987	425,5	505,0	518,5	13,5	0,027
428	411,5	513,5	503,4	-10,1	0,020
3282	419,5	493,0	494,0	1,0	0,002
3719	434,5	507,5	518,7	11,2	0,022
3720	402,5	465,5	479,5	14,0	0,030
5455	392,0	470,0	482,1	12,1	0,026

Erreur relative moyenne
1,95%

Second use case

- Adjusted parameters : f_d , u_d and L_d
- Learning on 10 animals (5 from the First Farm, 5 from the Second Farm)
- Fitting function for the Learning :
 - Weights after 64 days of the First Farm
 - Weights after 42 days for animals of the Second Farm
- Test on the 2 animals of the First Farm : Weights after 29 days, 64 days and 105 days
- Accuracy
 - at 29 days: 97%
 - at 64 days: 97%
 - at 105 days: 96%

Mutually Benefiting Interactions PDE - AI

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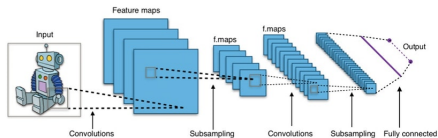
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Conclusion

- PDE based Artificial Intelligences (explained in this talk)
- Contribute understanding Deep Learning



- Analyse robustness of software tools via classical Machine Learning